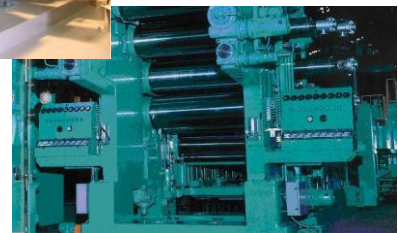# VF66

TOYO INTELLIGENT INVERTER

IO66-Z   Operating Manual

TOYO DENKI

Forword

Thank you for choosing Toyo VF66B inverter product.

This instruction manual contains information regarding the IO66-Z Optional Circuit Board for the VF66B Inverter. For correct use, please carefully read this instruction manual prior to using the IO66-Z.

In order to accommodate the many special functions to a wide variety of applications in addition to the basic inverter functions, please thoroughly read the instruction manual of the inverter as well as any other applicable specialized instruction manuals.

This instruction manual covers the functions, connection procedures for the IO66-Z, as well as guidelines for setting up the VF66B Inverter.

Please read before use

For safety

Before installing, operating, maintaining and inspecting IO66-Z option, please read this manual and all other appendices thoroughly in order to get familiarize with the feature of this option, safely information and correct handling. For safe operation, be sure to also thoroughly read the instruction manual of the inverter. In this instruction manual, the safety instructions are classified in to two levels: DANGER and CAUTION. These signs have important instructions. Please follow the instructions without fail.

⚠ **DANGER**	Indicates a hazardous situation which may result in death or serious injury if it is handled improperly.

⚠ **CAUTION**	Indicates a hazardous situation which may result in moderate or minor injury or only in property damage if it is handled improperly. However, such a situation may lead to serious consequences depending on circumstances.

⚠ CAUTION [Installation]

- Do not use optional circuit board if you discover damage or deformation during unpacking.
  Doing so may cause optional circuit board failure or malfunction.
- Do not place any flammable materials near the optional circuit board.
  Doing so may cause a fire.
- Do not allow the optional circuit board to drop, fall over or sustain severe impacts.
  Doing so may cause optional circuit board failure or damage.
- Do not install or operate the optional circuit board if it is damaged or has any of its parts missing.
  Doing so may lead to personal injury.

⚡ DANGER [Wiring]

- Before wiring, make sure the power is OFF.
  Failure to do so may cause an electric shock or fire.
- Wait more than 10 minutes after turning the power OFF before opening the unit case lid.
  Failure to do so may cause an electric shock or fire.
- Make sure that the unit is correctly earthed.
  Failure to do so may cause an electric shock or fire.
- Wiring must be done by skilled technicians.
  Failure to do so may cause an electric shock or fire.
- Wire the unit after it is installed.
  Failure to do so may cause an electric shock or fire.

⚠ CAUTION [Wiring]

- Make sure that communication cables and connectors are properly installed and locked in place.
  Failure to do so may cause optional circuit board failure or malfunction.

⚠ DANGER [Operation]

- Turn the power ON after fitting the inverter front cover.
  Do not remove the cover while the power is ON.
  Doing so may cause an electric shock.
- Do not operate any switch with wet hands.
  Doing so may cause an electric shock.
- Do not touch the inverter terminals while the power is ON, even if the inverter is in the idle state.
  Doing so may cause an electric shock.
- If the alarm is reset while the operation signal kept input, the inverter will suddenly restart. Reset the alarm after making sure that the operation signal is OFF.
  Failure to do so may lead to personal injury.
- The inverter can be set to operate in a wide range of speed. Operate the inverter after sufficiently checking the allowable range of the motor and equipment.
  Failure to do so may cause personal injury, equipment failure or damage.

⚠ CAUTION [Operation]

- The inverter radiating fin and the radiating resistance are hot. Do not touch them.
  Failure to follow this warning may cause burns.

⚠ DANGER [Maintenance, inspection and parts replacement]

- Always turn the power OFF before inspecting the inverter.
  Failure to do so may cause an electric shock, personal injury or fire.
- Unauthorized persons shall not perform maintenance, inspection or parts replacement.
  Use insulated tools for maintenance and inspection.
  Failure to do so may cause electric shock or personal injury.

⚠ DANGER [Other]

- Never modify the unit.
  Doing so may cause electric shock or personal injury.

⚠ CAUTION [General precautions]

Some illustrations given in this manual show the inverter from which the covers or safety shields have been removed to illustrate the details. Before operating the inverter, reinstall the covers and shields to their original positions and the inverter according to this manual.
These safety precautions and specifications stated in this manual are subject to change without notice.

Table of contents

Chapter 1 Functional outline

IO66-Z is used equipping the connector of the PC board (VFC66-Z) in a VF66B inverter. The functions with which IO66-Z is equipped are a multifunctional input/output function, an analog input/output function, and PG input/output function.

⚠ **CAUTION** [Safety precautions]

Carefully read the instruction manual before use, and use the inverter correctly.
 Our inverter and optional circuit board are not designed or manufactured for the purpose of use in life-support machines or systems.
 If you intend to use the product stated in this document for special purposes, such as passenger cars, medical devices, aerospace devices, nuclear energy controls and submarine relaying machines or systems, consult our sales department.
  This product is manufactured under strict quality control. However, if it is used in critical equipment in which inverter and optional circuit board failure may result in death or serious damage, provide safeguard to avoid serious accidents.
  If you wish to use this inverter with loads other than three-phase AC traction, please contact us.
  To use this product, electrical work is necessary. The electrical work must be done by qualified expert.

Chapter 2 Basic specification

2．1 Multifunction input/ output terminal specification

Multifunction input terminal

	Terminal No.	Use		Description
IO66-Z Terminal TB1	PS（2 Terminal）	Multifunction input	+12V power terminal	Output ＋12V of DC voltage
	G（2 Terminal）		GND terminal	Never connect GND terminal to the earth. Never touch nor connect PS terminal and G terminal.
	MI6		Multifunction input terminal (6)	(Maximum input voltage DC24V/Maximum input current 3mA) By input the signal in multifunction input terminal, the same operation can be done as that of console. [In the initial condition, the VF66B inverter setting parameter for the C area are set to:
	MI7		Multifunction input terminal (7)	・For multifunction input terminal (6), preset speed selection 1 ・For multifunction input terminal (7), preset speed selection 2
	MI8		Multifunction input terminal (8)	・For multifunction input terminal (8), preset speed selection 3
	MI9		Multifunction input terminal (9)	・For multifunction input terminal (9), Accel./decel time selection 1 ・For multifunction input terminal (10), Accel./decal.time selection 2
	MI10		Multifunction input terminal (10)	・For multifunction input terminal (11), speed up command]
	MI11		Multifunction input terminal (11)	※See the instruction manual of the inverter for details of multifunction input terminals.

	Connector	Use	Description
IO66-Z Jumper connector	CN-SO	Source mode	・Setting source mode／sink mode is conducted by replacement of jumper socket CN-SI, CN-SO. ・In replacement of jumper socket, please cut off the power supply. [In the initial condition, the source mode is set.] ・In case of source mode, the switch etc. is connected between multifunction input terminal (6) to (11) and PS terminal, and turn on/off.
	CN-SI	Sink mode	・In case of sink mode, the switch etc. is connected between multifunction input terminal (6) to (11) and G terminal, and turn on / off. For the detail information, please see the Chapter 4.

Multifunction output terminal

	Terminal No.	Use		Description
IO66-Z Terminal TB1	P	Multifunction output	External power supply connecting terminal	P terminal is connected to the external power supply(DC).
	COM		Common potential connection terminal	Never connect COM terminal to the earth.
	MO3		Multifunction output terminal (3)	(Max. voltage DC24V/Max. Output current 20mA) Multifunction output terminal outputs the signal depends on the situation of performance. [In the initial condition, the followings are set by VF66 inverter setting parameter：H area. ・For multifunction output terminal (3), no use.
	MO4		Multifunction output terminal (4)	・Multifunction output terminal (4), torque detected.] ※Refer to the instruction manual of the inverter for the details of a multifunctional input terminal.

２．２ Analog input/ output terminal specification

Analog input output function

	Terminal No.		Use	Description
IO66-Z Terminal TB1	AIN2	Analog Input	Analog input (2) terminal	・Type of input can be selected from 0 to ±10V, 0 to 10V, 4 to 20mA by the swift of SW1 and alternation of inverter setting parameter. （Please refer to Chapter 5 for the change of the input range.） ・Input resistance is 150kΩ in input analog voltage. ・Input resistance is 250Ω in input analog current. ・Use 10kΩ in frequency command and rotation speed command by variable resistor. ・Analog input is isolated from analog output. [In the initial condition, 0 to ±10V is set.] ※See the instruction manual of the inverter for details of analog input terminal (2).
	AIN3		Analog input (3) terminal	・Type of input can be selected from 0 to ±10V, 0 to 10V, pulse train which （0 to 150kHz pulse input at peak value voltage 15V, duty1:1 ） by the swift of SW3 and alternation of inverter setting parameter. （See the chapter 5.） ・Input resistance is150kΩ in input analog voltage. ・Use 10kΩ in frequency command and rotation speed command by variable resistor. ・Analog input is isolated from analog output [In the initial condition, 0 to 10V is set] ※See the instruction manual of the inverter for details of analog input terminal (3).
	G-IN		GND terminal	Never connect G-IN terminal to the earth.
	AOT2	Analog output	Analog output (2) terminal	・Output 0 to ±10V. ・Max. current is 1mA. ・Analog input is isolated from analog output. [In the initial condition, it is set to output the output current.] ※See the instruction manual of the inverter for details of analog output terminal (2).
	AOT3		Analog output (3) terminal	・Type of input can be selected from 0 to ±10V, 4 to 20mA by swift of SW5 and alternation of inverter setting parameter. （See the chapter 5.） ・Max. current is 1mA in output analog voltage. ・Analog output is isolated from analog Input. [In the initial condition, it is set to output the output voltage.] ※See the instruction manual of the inverter for analog output terminal (3).
	G-OT		GND terminal	Never connect G-OT terminal to the earth.

２．３ PG input/output terminal specification

PG input/output function

	Terminal No.	Use	Description
IO66-Z Terminal TB2	+12	+12V power terminal	Output +12V of DC voltage
	G (3 terminals)	GND terminal	Never connect GND terminal to the earth.
	A	PG input terminal	Input A, B, U/Z, V, and W signal (complementary output) of 12 V power PG respectively.
	B		
	U/Z		
	V		
	W		
	PG-OUT	PG output terminal	Outputs a divided waveform of the PG A-signal.

2．4 Other

Other standard specifications apply to VF66B inverter correspondingly. For more details, please refer to the instruction manual of the inverter.

⚠ DANGER [Wiring]

- Before wiring, make sure the power is OFF.
  Failure to do so may cause an electric shock or a fire.
- Substitution of Jumper socket is performed after certainly turning off an inverter.
  Failure to do so may cause an electric shock, personal injury, equipment failure or malfunction.

⚠ CAUTION [Wiring]

- G terminal, G-IN terminal, and G-OT terminal are not connected to a grounding by any means.
  Doing so may cause equipment failure or damage.
- Never connect or allow contact between the PS and G terminals.
  Doing so may cause equipment failure or damage.

Chapter 3 Description of substrate

3．1 Name of each part

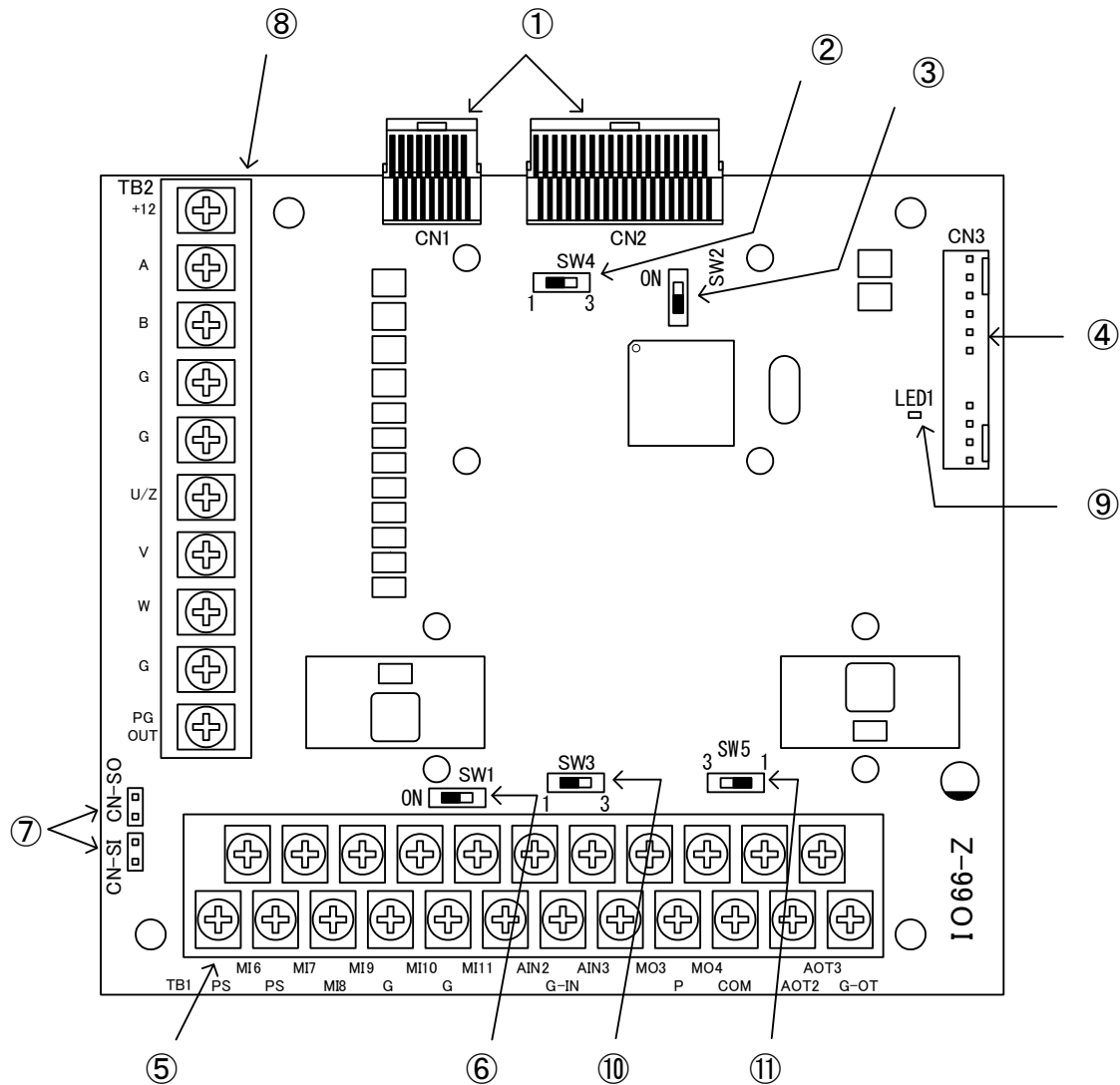
Figure3.1 IO66-Z substrate

① Connector to VFC66-Z (CN1,2)

② PG frequency dividing output switch (SW4)

③ PG signal ON/OFF switch (SW2)

④ Connector to external extension option"IOEXT66" (CN3)

⑤ Multi function input/output, analog input/output terminal block (TB1)

⑥ Analog input(2) signal characteristic switching switch (SW1)

⑦ Multi function input signal characteristic switching jumper connector (CN-SI, CN-SO)

⑧ PG input/output terminal block (TB2)

⑨ LED for operation check of CPU of IO66-Z

⑩ Analog input (3) signal characteristic switching switch (SW3)

⑪ Analog output (3) signal characteristic switching switch (SW5)

As connector connecting to ④, please use housing :5051-12, terminal coated gold :2759G or 2759PBG produced by Molex. For connection to CN3 and usage of CN3 and so on, please refer to the instruction manual about IOEXT66.

3．2 IO66-Z switches

You can change various function by switching the switch on IO66-Z.

Each kind of function of switch on IO66-Z

Name of switch	Use	Description
SW1	Analog input(2) signal characteristic switching switch	Switch input signal characteristic of analog input (2) terminal. ・0 to 10V, 0 to ±10V input when the switch is OFF. ・4 to 20mA input when the switch is ON. [In the initial condition, the switch is set to OFF.] ※When you switch input range, please change the parameter of VF66B inverter. For more detail, please refer to chapter 5.
SW2	PG signal ON/OFF switch	Switch ON/OFF PG signal. ・PG signal is no effect when the switch is OFF. ・PG signal is available when the switch is ON. [As default, the switch is ON.]
SW3	Analog input(3) signal characteristic switching switch	Switch input signal characteristic of analog input (3) terminal. ・0 to 10V, 0 to ±10V input when the switch is side of 3. ・Pulse train input when the switch is side of 1. [As default, the switch is side of 3.] ※When you switch input range, please change the setting parameter of VF66B inverter. For more detail, please refer to chapter 5.
SW4	PG frequency dividing output switch	Switch output of PG frequency dividing signal. ・1/4 frequency dividing signal is output when the switch is side of 3. ・1/2 frequency dividing signal is output when the switch is side of 1. [In the initial condition, the switch is set to position "3".]
SW5	Analog output (3) signal characteristic switching switch	Switch output signal characteristic of analog output (3) terminal. ・0 to 10V, 0 to ±10V output when the switch is side of 3. ・4 to 20mA output when the switch is side of 1. [As default, the switch is side of 3.] ※When you switch input range, please change the setting parameter of VF66B inverter. For more detail, please refer to chapter 5.

⚠ DANGER [Switch]

● Change of a switch is performed by certainly turning off the inverter.
Failure to do so may cause an electric shock, personal injury, equipment failure or malfunction.

３．３ **Installation of IO66-Z**

VFC66-Z circuit board

Connectors

Optional circuit board

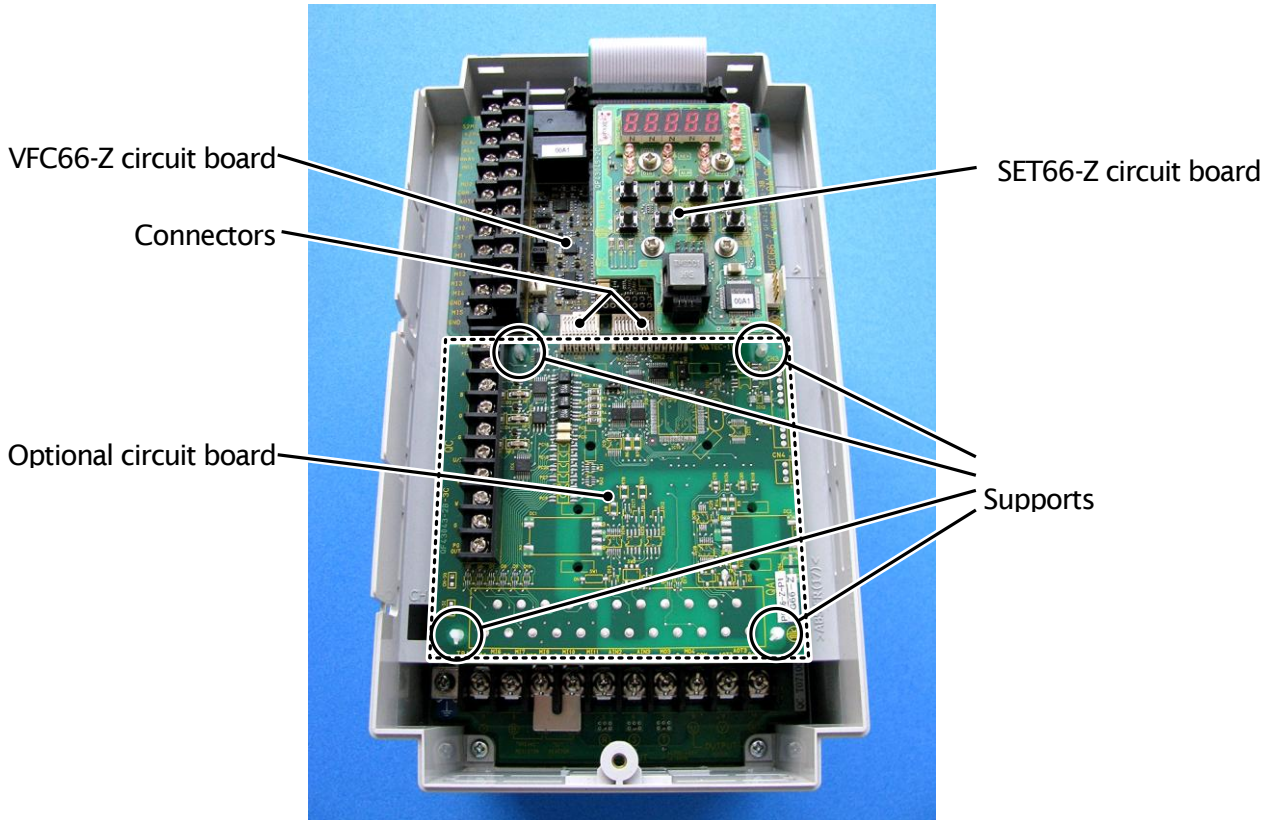SET66-Z circuit board

Supports

Figure 3.2 Optional circuit board installation position (VF66B-2R222)

*For information about opening and closing the front cover of the inverter, please refer to the instruction manual of the inverter.

(1) Confirm that the power is off before performing any work.

(2) Install the IO66-Z board in the location designated by the dotted lines shown in Figure 3.2. (The figure shows the VF66B-2R222 model, however, the installation location is the same for other models.) If another optional circuit board is already installed, remove it by following the procedure described below. If another optional circuit board is not already installed, skip to (6).

(3) In order to safely remove the optional circuit board, first remove the SET66-Z board. Remove the 4 screws indicated by the circles in the figure on the right. Pull the SET66-Z board away from the VFC66-Z board in order to detach it.

(4) Next, release the two connectors between the VFC66-Z board and the optional circuit board. Figure 3.4 (a) shows the connector in its engaged position. Pull up the tab to release the connector as shown in Figure 3.4 (b).

(5) 4 board supports are included to mount the optional circuit board to the inverter housing, as indicated by the circles in Figure 3.2. Press down on the board support locking hooks as shown in Figure 3.5 to remove the optional circuit board.
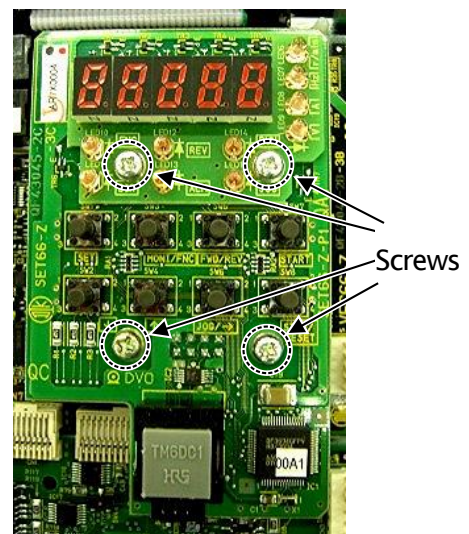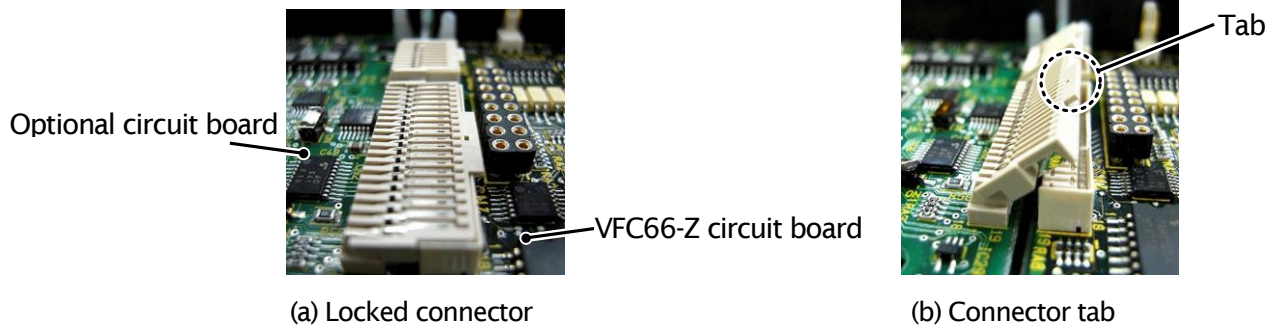

Screws

Figure 3.3 SET66-Z circuit board

11

Optional circuit board

VFC66-Z circuit board

(a) Locked connector

Tab

(b) Connector tab

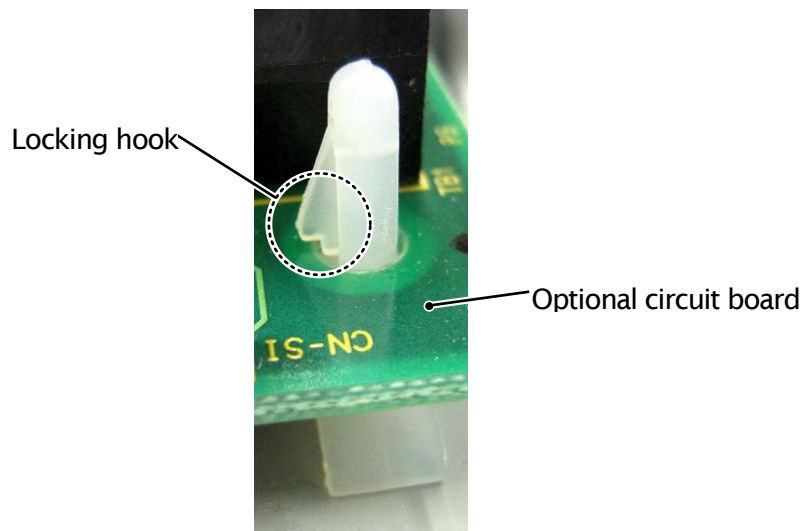Figure 3.4 Connector

Locking hook

Optional circuit board

Figure 3.5 Support locking hook

(6) Align the four holes of the IO66–Z board with the 4 board supports indicated by the circles in Figure 3.2. Push down on the board until the support locking hooks snap into place as shown in Figure 3.5.

(7) Align the tabs (shown in Figure 3.4 (b)) of the IO66–Z board connectors CN1 and CN2 with the VFC66–Z board connectors CN7 and CN4. Press down on the tabs to engage with the connectors. Once the connectors are correctly joined, it will look like Figure 3.4 (a). The movable part of the connector has some elasticity and if the joint is weak, it may become disconnected. Ensure that is it properly locked in place.

(8) Install the SET66–Z board to its original position.

(9) Return the front cover of the inverter to its original position.

⚡ DANGER [Installation/Removal]

- Always confirm that the power is off before installing/removing any circuit boards.
  Failure to do so may cause an electric shock, personal injury, equipment failure or malfunction.　B

⚠ **CAUTION** [Installation/Removal]
● Avoid excess connection and disconnection of the connectors.   The connector mounting area may become loose, leading to problems such as poor connections.   ● Do not attempt to insert any object other than a compatible connector.   The connector mounting area may deform, leading to problems such as poor connections.

３．４ LED operation

• **LED1 operation**

LED1 illuminates in a cycle of about 2 seconds when IO66-Z is operating normally. If LED1 is not illuminated properly when power is on, the following situations may be the cause:

➢ **The connection between VFC66-Z and IO66-Z may be faulty.**

➢ **VFC66-Z or IO66-Z may be malfunctioning.**

⚠ **CAUTION** [Safety Precautions]
● If LED1 is not operating normally, the IO66-Z or VFC66-Z board may be malfunctioning.   If this is the case, please contact us immediately.

Chapter 4 Multifunction input/ output specification

4．1 **Multifunction input**

1. Source mode (with internal power source)

2. Source mode (with external power source)

3. Sink mode (with internal power source)
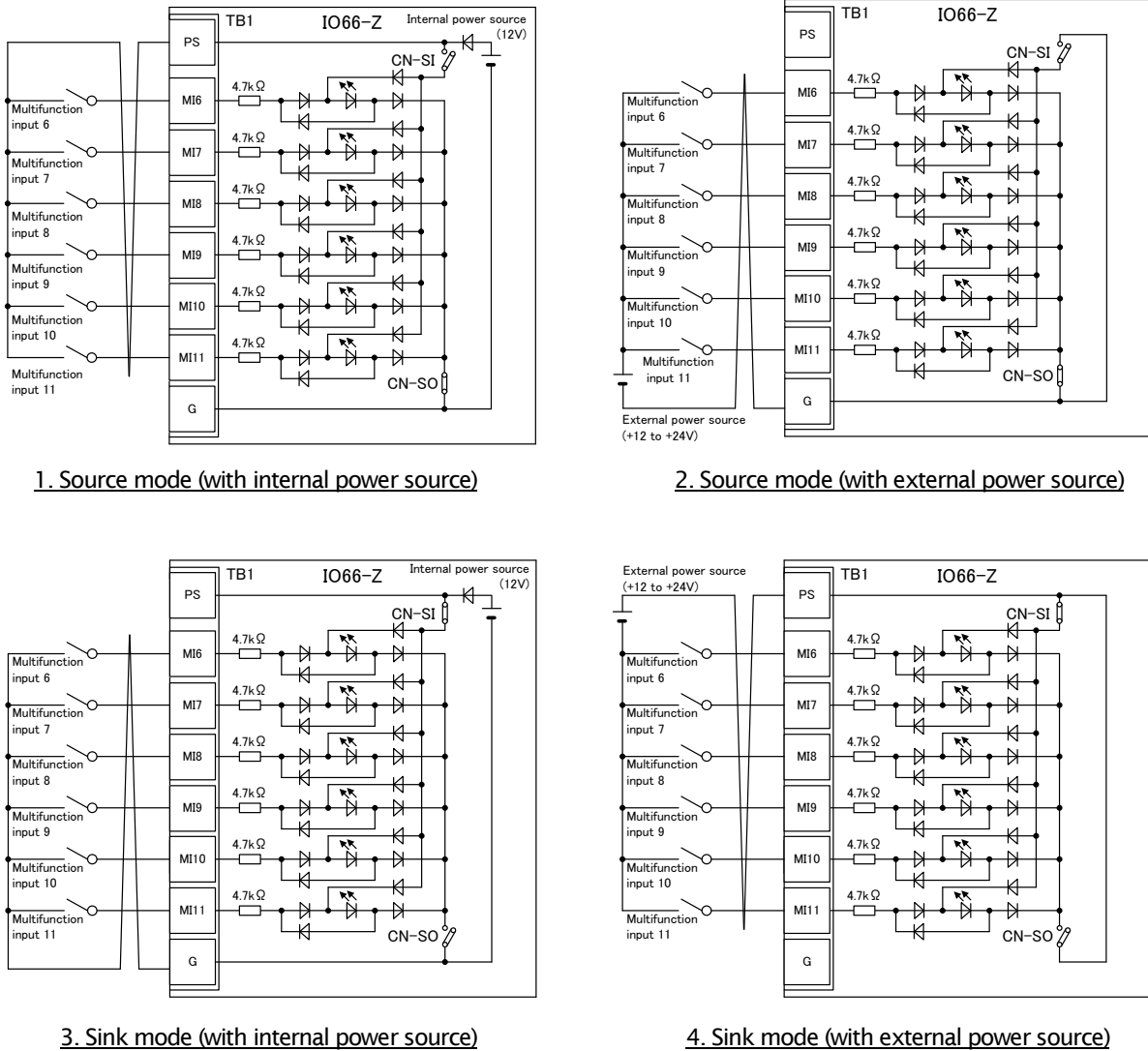
4. Sink mode (with external power source)

Figure 4.1 Multifunction input connections

The IO66-Z can use the VF66B inverter multifunction input. The above figures show typical multifunction input signal connection methods. The **maximum allowable voltage is 24V** and the **maximum allowable current for any one terminal is 3mA**. For more information about the functions of the individual multifunction input terminals, please refer to the instruction manual of the inverter.

The multifunction input signal can be set to either source mode or sink mode and an internal power source or external power source can be chosen for the inverter. In the initial configuration, it is set to source mode. To switch between source mode and sink mode, place a jumper shunt on either the IO66-Z jumper connector CN-SO (source mode) or CN-SI (sink mode).

Multifunction input related inverter parameters

Display	Items	Item Selection	Default Data	Unit
c-00	Multifunction input place selection	0: Terminal block 1: Digital communication option	0: Terminal block	—

c-06	Multifunction input terminal (6) function selection	0: Preset frequency selection 1 (V/f mode)
		   Preset rotation speed selection 1 (vector mode)
		1: Preset frequency selection 2 (V/f mode)
		   Preset rotation speed selection 2 (vector mode)
		2: Preset frequency selection 3 (V/f mode)
		   Preset rotation speed selection 3 (vector mode)
		3: Acceleration/deceleration time selection 1
		4: Acceleration/deceleration time selection 2
		5: Frequency UP command (MRH mode) (V/f mode)
		   Rotation speed UP command (MRH mode) (vector mode)
		6: Frequency DOWN command (MRH mode) (V/f mode)
		   Rotation speed DOWN command (MRH mode) (vector mode)
		7: Frequency hold (V/f mode)
		   Rotation speed hold (vector mode)
		8: S-pattern acceleration/deceleration prohibition
		9: Max. frequency reduction (V/f mode)
		   Max. rotation speed reduction (vector mode)
		10: Droop control disabled
			0:Preset frequency selection 1	—

c-07	Multifunction input terminal (7) function selection		1:Preset frequency selection 2	
c-08	Multifunction input terminal (8) function selection		2:Preset frequency selection 3	
c-09	Multifunction input terminal (9) function selection		3:Acceleration/ deceleration time selection 1	
c-10	Multifunction input terminal (10) function selection		4:Acceleration/ deceleration time selection 2	
c-11	Multifunction input terminal (11) function selection		5:Frequency UP command	

		11: No function (V/f mode)
		    Speed/torque control selection (vector mode)
		12: Forward/reverse operation command selection
		13: DC brake command
		14: No function (V/f mode)
		    Initial excitation command (vector mode)
		15: External failure signal 1 (protection relay 86A enable)
		16: External failure signal 2 (protection relay 86A enable)
		17: External failure signal 3 (protection relay 86A enable)
		18: External failure signal 4 (protection relay 86A enable)
		19: External failure signal 1 (protection relay 86A disabled)
		20: External failure signal 2 (protection relay 86A disabled)
		21: External failure signal 3 (protection relay 86A disabled)
		22: External failure signal 4 (protection relay 86A disabled)
		23: Trace back external trigger
		24: Second set-up block selection
		25: Emergency stop (B contact)
		26: No function
		27: Frequency commanding terminal block selection (V/f mode)
		    Rotation speed commanding terminal block selection (vector mode)
		28: No function
		29: Operation command [reverse] (STARTR)
		30: Jog command [forward] (JOGF)
		31: Jog command [reverse] (JOGR)
		32: Emergency stop (A contact)
		33: Protection reset (RESET)
		34: External signal input 1
		35: External signal input 2
		36: External signal input 3
		37: External signal input 4		

The IO66-Z multifunction input signal can also be used as the VF66B inverter built-in PLC function input relay. For more information, please refer to the instruction manual of the inverter and the VF66 PCTool manual.

<table>
<tr><td colspan="2" align="center">⚠ **DANGER** [Wiring]</td></tr>
</table>

⚠ DANGER [Wiring]

- Before wiring, make sure the power is OFF.
  Failure to do so may cause an electric shock or a fire.
- Substitution of Jumper socket is performed after certainly turning off an inverter.
  Failure to do so may cause an electric shock, personal injury, equipment failure or malfunction.

⚠ CAUTION [Wiring]

- G terminal, G-IN terminal, and G-OT terminal are not connected to a grounding by any means.
  Doing so may cause equipment failure or damage.
- Never connect or allow contact between the PS and G terminals.
  Doing so may cause equipment failure or damage.

４．２ Multifunction output

1. Connection with PLC (Source mode)

2. Connection with PLC (Sink mode)

3. Connection with Relay
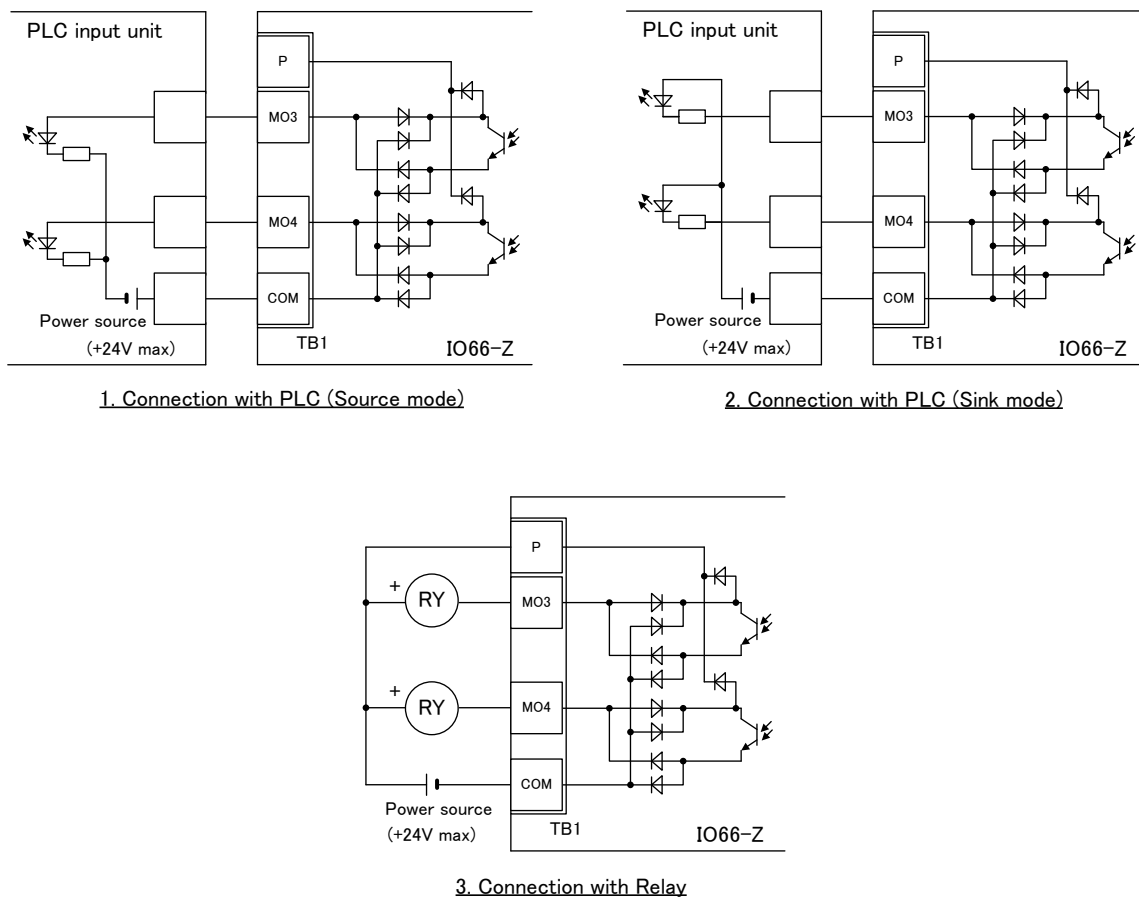
Figure 4.1 Multifunction output connections

The IO66-Z can use the VF66B inverter multifunction output. The above figures show typical multifunction output signal connection methods. Multifunction output is open corrector output of transistor. In order to use it, DC power supply are required for the exterior. The **maximum allowable voltage is 24V** and the **maximum allowable current for any one terminal is 20mA**. For more information about the functions of the individual multifunction output terminals, please refer to the instruction manual of the inverter.   B

Multifunction output related inverter parameters

Display	Items	Item Selection	Default Data	Unit
H-02	Multifunction output terminal (3) function selection	0: not used 1: Frequency detection (1) (V/f mode) (Frequency = detection setting) Motor speed detection (1) (vector mode) (Motor speed = detection setting) 2: Frequency detection (1) (V/f mode) (Frequency ≧ detection setting) Motor speed detection (1) (vector mode) (Motor speed ≧ detection setting) 3: Frequency detection (1) (V/f mode) (Frequency ≦ detection setting) Motor speed detection (1) (vector mode) (Motor speed ≦ detection setting) 4: Frequency detection (2) (V/f mode) (Frequency = detection setting) Motor speed detection (2) (vector mode) (Motor speed = detection setting) 5: Frequency detection (2) (V/f mode) (Frequency ≧ detection setting) Motor speed detection (2) (vector mode) (Motor speed ≧ detection setting) 6: Frequency detection (2) (V/f mode) (Frequency ≦ detection setting) Motor speed detection (2) (vector mode) (Motor speed ≦ detection setting) 7: Reach setting 8: Torque detection 9: Torque detection (absolute value) 10: Power failure 11: Overload pre-alarm 12: Restart mode 13: In reverse operation 14: Protection operation code 15: not used 16: In operation 17: Extended schedule function(Usually, not set up) 18: Timer 1 setup time passes 19: Timer 2 setup time passes 20: 2nd set-up block selected 21: Cooling fan failed 22: DB abnormal state	0:not used	—
H-03	Multifunction output terminal (4) function selection		1:Torque detection	

When connecting a PLC input unit outside, IO66-Z can choose a connection in sink mode and source mode. Recommends using a twist line to a product line of PLC and IO66-Z. When connecting a relay externally, a coil uses a relay of a direct-current operation (for example, OMRON: G7T-112S-DC 24V etc.). Since IO66-Z builds in the reflux diode which controls surge voltage, it certainly connects the + side terminal of external power source to P terminal of a terminal block in IO66-Z.

   The IO66-Z multifunction output signal can also be used as the VF66B inverter built-in PLC function output relay. For more information, please refer to the instruction manual of the inverter and the VF66 PCTool manual.

⚠ CAUTION [Wiring]

- Before wiring, make sure the power is OFF.
  Failure to do so may cause an electric shock or a fire.
- G terminal, G-IN terminal, and G-OT terminal in terminal block 1 are not connected to a grounding by any means.
  Doing so may cause equipment failure or damage.

Chapter 5 Analog input/output function

5．1 Analog input (2)

The analog input (2) to the terminals on IO66-Z can be used as the input value to the rotation speed command value (or frequency command value), torque command value, and built-in PLC function by analog input (2) function.

For usage of analog input (2) function correctly, the correct VF66B inverter parameter setting as mentioned below is required. Please see the instruction manual of the inverter together. Furthermore, for the built-in PLC function, please see VF66 PC Tool manual.

Before usage of analog input (2), please conduct the adjustment of gain as mentioned below.

Analog input (2) characteristic selection (when IO66-Z option or digital communication option is used)

Display	Item	Set-up range (Item selection)	Default Data	Unit
G-03	Analog input(2) characteristics selection	0:0 to ±10V 1:0 to 10V 2:4 to 20mA	1	—

* If setting the torque command value as analog input (2), set this to "0". Only the 0 to ±10V voltage input characteristic can be used.

The analog signal input into analog Input (2) should be connected between the [AIN2] and [G2] terminals of the IO66-Z terminal block TB1, as shown in the following figures. The input analog signal characteristics can be chosen as either "voltage input 0 to ±10V", "voltage input 0 to 10V" or "current input 4 to 20mA", as shown in the above table. Choose an appropriate setting that matches the characteristics of the input signal. Also set the SW1 switch as shown in the following figures.
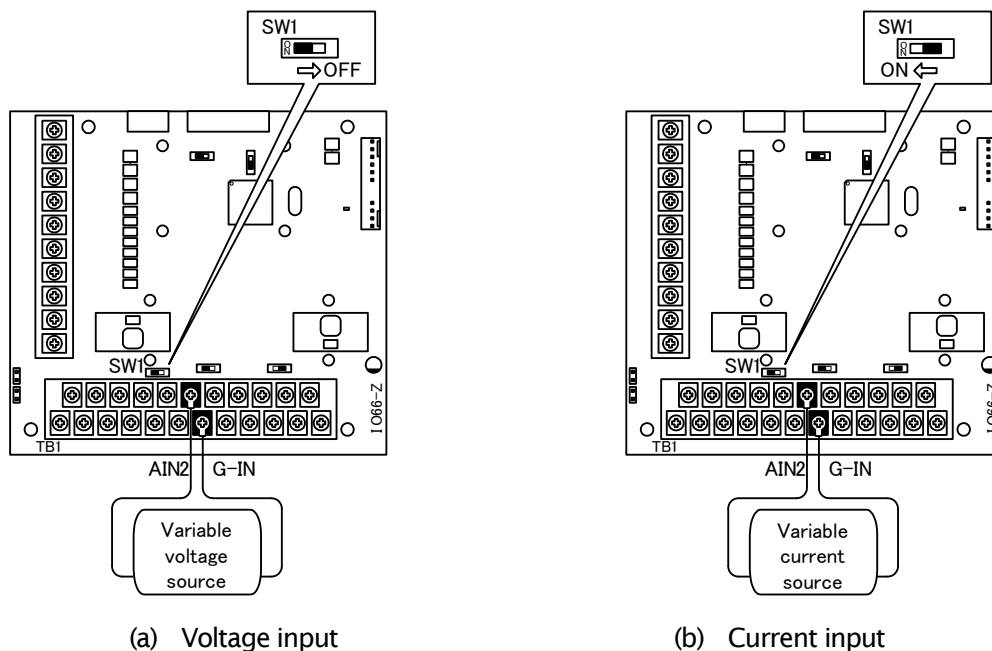

(a) Voltage input   (b) Current input

Figure 5.1 Connection of analog input (2)

５．２ Analog input (2) input gain and offset adjustment

Before usage of analog Input (2), gain and offset adjustment are required. Adjustment is conducted under the temperature about 25℃.

Inverter setting parameter related to analog input (2) gain and offset adjustment

Display	Items	Set-up range (Item selection)	Default Data	Unit
L-05	Analog input(2) gain	50.00 to 150.00	100.00	%
L-06	Analog input(2) offset	-50.00 to 50.00	0.00	%
S-08	Analog input(2) adjust	1. Analog input (2) offset adjustment Input the analog(2) voltage x 1000 Analog input(2) gain adjustment	-	-

（1）Input characteristics "0 to ±10V" or "0 to 10V"

`09-FF` Press [MONI/FNC] key to turn on FNC (function selection) mode (LED-FNC will be lit).

`G-03` Use [↑][↓]keys to select 「G-03」 and press [SET] key to confirm it.

`0` Use [JOG/→]key to shift the digit to right、 and [↑][↓]keys to input "0" and press [SET]keys to confirm it.

<IO66-Z>
terminal block
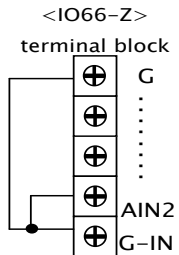
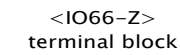Turn Off the inverter, open the front cover, and short circuit between [AIN2] [G] [G-IN] terminal on the terminal block <TB1> of the <IO66-Z>.

G
AIN2
G-IN

⚠ **CAUTION** [Short-Circuit of terminals]
● Before short circuiting terminals, please be sure to turn OFF the inverter.
There is a risk of electrical shock.

`S-08` After power is ON, press [MONI/FNC] key to turn on FNC (function selection) mode. (LED-FNC will be lit). Use[JOG/→] [↑][↓]keys to select 「S-08」,and press [SET] key to confirm it.
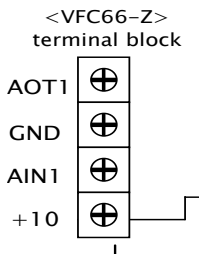
`1040` Use [JOG/→] [↑][↓]keys to input 「1040」 and press[SET]key to confirm it.
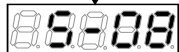
`S-08` 「S-08」 will appear again, press[SET]key to confirm.

`1` Use [JOG/→] and [↑][↓]keys to select "1" and press[SET]key to confirm it.

<VFC66-Z>   <IO66-Z>
terminal block   terminal block

Turn OFF the inverter, open the front cover, and short circuit between [AIN2] on the terminal block <TB1> of the <IO66-Z> and [+10] on the terminal block <TB1> of the control board <VFC66-Z>. Remain short circuited terminals between [G] and [G-IN] of the <IO66-Z>.

AOT1
GND
AIN1
+10

G
AIN2
G-IN

⚠**CAUTION**[Short-Circuit of terminals]
● Before short circuiting terminals, please be sure to turn OFF the inverter.
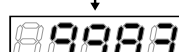There is a risk of electrical shock.

`S-08`
`1040`
`S-08`

· After power is ON, press[MONI/FNC]key to turn on FNC (function selection) mode. (LED-FNC will be lit) then, use [JOG/→] [↑][↓]keys to select 「S-08」 and press [SET]key to confirm.
· Use [JOG/→] [↑][↓]keys to change numbers, Input 「1040」 and press [SET]key to confirm.
· 「S-08」 will appear again、 press [SET]key to confirm.

`9930` Measure the voltage between the <IO66-Z> terminals [AIN2] and [GND] with a tester and enter the 1000times of the measured value. If measurement is not available, the value"9930" can be used. However accuracy is inferior

⚠ **CAUTION**[Voltage measurement]
When the voltage between the terminals is measured, please be sure not to touch wirings or terminals. There is a risk of electrical shock.
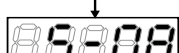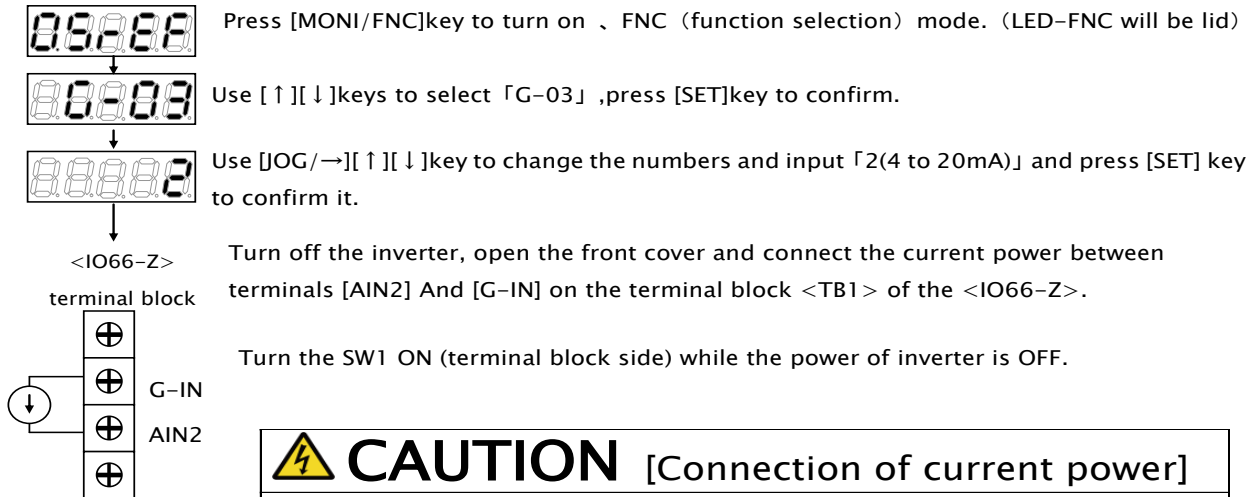
`S-08` If 「S-08」appears again, analog input (2) gain(L-05) and analog input (2) offset(L-06) will be changed automatically. Press [MONI/FNC] Key to indicate monitor items.

When adjustment is done, turn OFF the inverter, open the front cover and remove the short circuit wirings installed between terminals, [AIN2]and [+10] of the control board <VFC66-Z>, as well as [G] and [G2] on the <IO66-Z>.
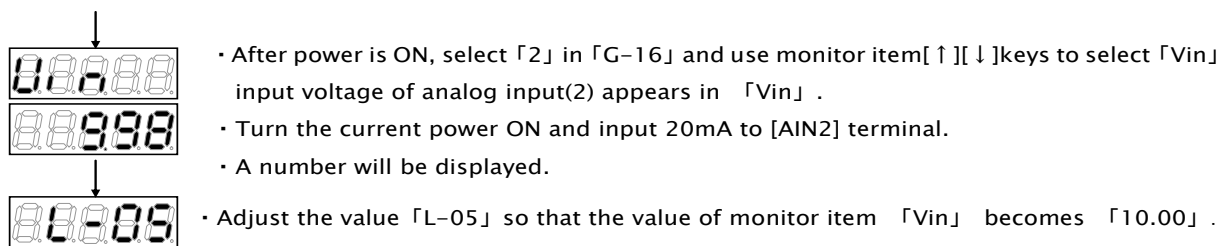
（2）**Input characteristics of "4 to 20mA"**

※Conduct this after adjustment of aforementioned "(1) if the input characteristics is 0 to ±10V or 0 to 10V"

`05-88` Press [MONI/FNC]key to turn on 、FNC（function selection）mode.（LED-FNC will be lid）

`G-03` Use [↑][↓]keys to select「G-03」,press [SET]key to confirm.

`2` Use [JOG/→][↑][↓]key to change the numbers and input「2(4 to 20mA)」and press [SET] key to confirm it.

<IO66-Z>
terminal block

⊕

⊕ G-IN

⊕ AIN2

⊕

Turn off the inverter, open the front cover and connect the current power between terminals [AIN2] And [G-IN] on the terminal block <TB1> of the <IO66-Z>.

Turn the SW1 ON (terminal block side) while the power of inverter is OFF.

┌───┐
│ ⚡ **CAUTION** [Connection of current power]   │
├───┤
│ ● Before connecting current power, please be sure to turn OFF the inverter. │
│   There is a risk of electrical shock. │
│ ● Please be sure to turn OFF the inverter before switching a switch. │
│   There is a risk of electrical shock. │
└───┘

`00.00`
`9.98`
`L-05`

・After power is ON, select「2」in「G-16」and use monitor item[↑][↓]keys to select「Vin」input voltage of analog input(2) appears in 「Vin」.
・Turn the current power ON and input 20mA to [AIN2] terminal.
・A number will be displayed.
・Adjust the value「L-05」so that the value of monitor item 「Vin」 becomes 「10.00」.

When adjustment is done, remove the current power.

5．3 Analog input (2) usage instructions

Before using the analog Input (2) function, perform gain and offset adjustment as described in the preceding section.

Through the analog input (2), the input analog signal can be set to be the rotation speed command value (or frequency command value), torque command value or built-in PLC input value. The following explanation is for when it is set as the rotation speed command value or the torque command value. For instructions when using it as the input value to the built-in PLC, please refer to the VF66 PCTool manual.

（1）When using the input as a rotation speed command value

When using the analog input as a rotation speed command value, the inverter configuration parameters shown in the following table must be set.

Analog input rotation speed command settings

Display	Items	Set-up Range (Item Selection)	Default Data	Unit
b-10	Rotation speed commanding input place selection	0: Coupled with b-09 1: Analog input (1) [VFC66-Z terminal block AIN1] 2: Console [SET66-Z] 3: Digital communication option 4: Analog input (2) [Optional terminal block AIN2] 5: <BCD66-Z> 6: Analog input (3) [Optional terminal block AIN3] 7: Built-in PLC function output	0	—
G-04	Analog input (2) rotation speed upper limit	[Absolute value of analog input (2) rotation speed lower limit (G-05)] to [100.0][*]	100.0	%[*]
G-05	Analog input (2) rotation speed lower limit	-[Analog input (2) rotation speed upper limit (G-04)] to [Analog input (2) rotation speed upper limit (G-04)][*]	0.0	%[*]

(*) This is set as a percentage with respect to the maximum rotation speed (configuration parameter A-00). For information about configuration parameter A-00, please refer to the instruction manual of the inverter.

- Set b-10 to "4".
- Set G-03 (described in section 5.1) to a set value that matches the input signal characteristics.

・In the case of voltage input of 0 to ±10V

The rotational direction can be reversed by setting the command input voltage to a negative value. The rotation speed command value is set as the analog input (2) rotation speed upper limit (G-04) when the input is +10V. When the input is -10V, it is set as the negative value of the analog input (2) rotation speed upper limit (G-04). However, it is possible to set a lower limit by setting the analog input (2) rotation speed lower limit (G-05). (Figure 5.2, left)If the minimum rotation speed (A-01) is other than "0", the rotation speed command absolute value is controlled to prevent falling below the minimum speed. In this case, when the command input voltage is around the 0V range, its behavior shows hysteresis characteristics (It will run forward if started in the forward direction and will run in the minimum reverse speed if started in the reverse direction) as shown in the right side of Figure 5.2.
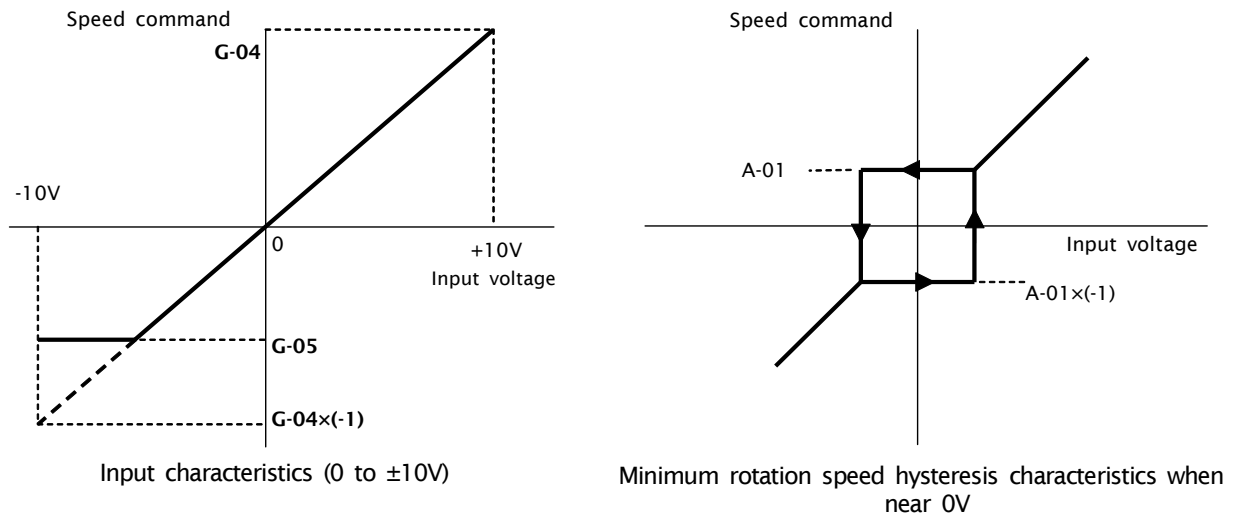

Input characteristics (0 to ±10V)

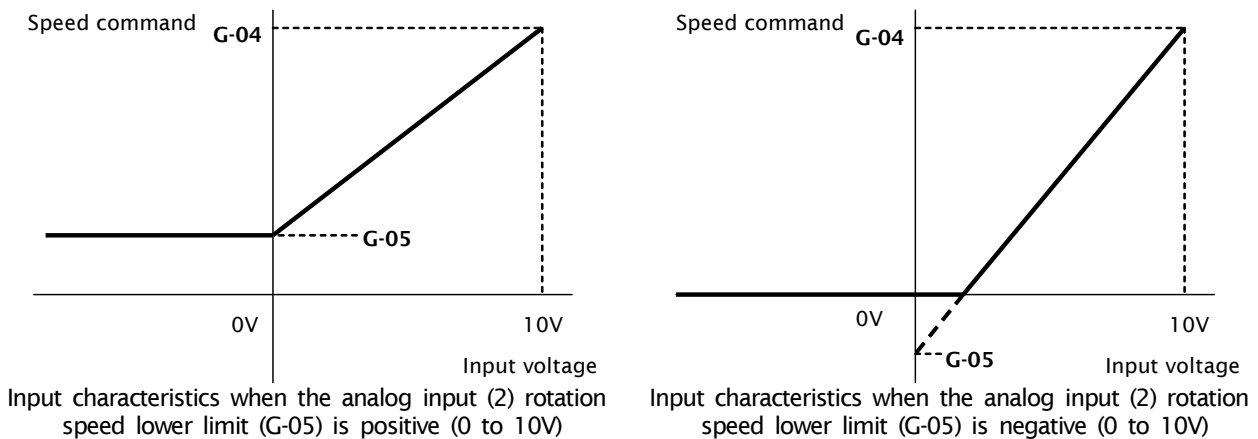Minimum rotation speed hysteresis characteristics when near 0V

Figure 5.2 Speed command characteristics with voltage input of 0 to ±10V

· In the case of voltage input of 0 to 10V

The rotation speed command value is set as the analog input (2) rotation speed lower limit (G-05) when the input is 0V. When the input is 10V, it is set as the analog input (2) rotation speed upper limit (G-04). However, this will be set to "0" if the analog input (2) rotation speed lower limit (G-05) has a negative value. (Figure 5.3) If the minimum rotation speed (A-01) is other than "0", the rotation speed command absolute value is controlled to prevent falling below the minimum speed. As a speed command, this only allows forward operation. For reverse operation, a reverse operation command should be used.
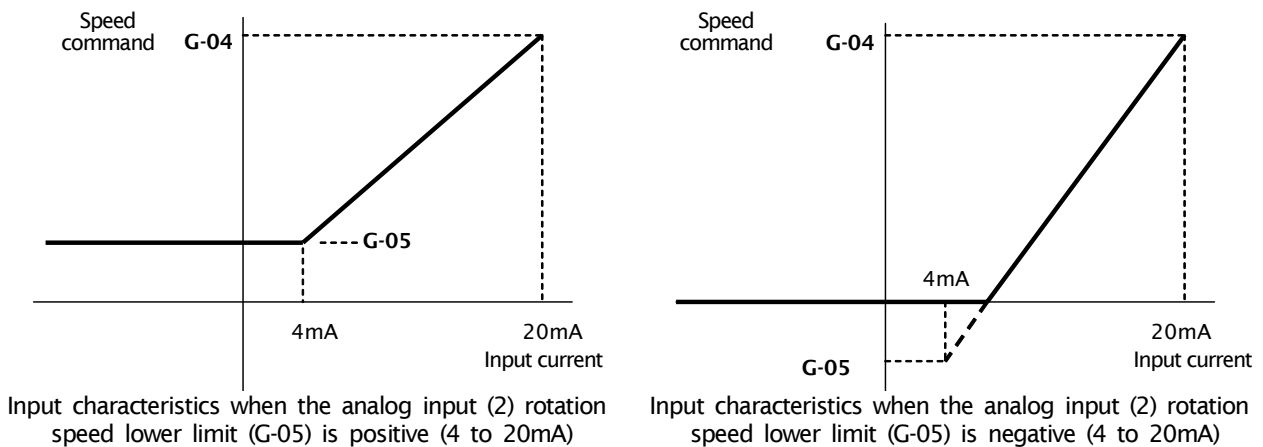

| Input characteristics when the analog input (2) rotation speed lower limit (G-05) is positive (0 to 10V) | Input characteristics when the analog input (2) rotation speed lower limit (G-05) is negative (0 to 10V) |

Figure 5.3 Speed command characteristics with voltage input of 0 to 10V

· In the case of current input of 4 to 20mA

The rotation speed command value is set as the analog input (2) rotation speed lower limit (G-05) when the input is 4mA. When the input is 20mA, it is set as the analog input (2) rotation speed upper limit (G-04). However, this will be set to "0" if the analog input (2) rotation speed lower limit (G-05) has a negative value. (Figure 5.4) If the minimum rotation speed (A-01) is other than "0", the rotation speed command absolute value is controlled to prevent falling below the minimum speed. As a speed command, this only allows forward operation. For reverse operation, a reverse operation command should be used.

| Input characteristics when the analog input (2) rotation speed lower limit (G-05) is positive (4 to 20mA) | Input characteristics when the analog input (2) rotation speed lower limit (G-05) is negative (4 to 20mA) |

Figure 5.4 Speed command characteristics with current input of 4 to 20mA

（2） **When using the input as a torque command value**

When using the analog input as a torque command value, the inverter configuration parameters shown in the following table must be set.

* **Torque command is disabled in V/f mode.**
* **The 4 to 20mA current input characteristic cannot be used for the torque command value. Only the 0 to ±10V voltage input characteristic can be used.**

Inverter configuration parameters related to analog input torque command

Display	Items	Set-up Range (Item Selection)	Default Data	Unit
i-08	Torque command input place selection	0: Analog input (1) [VFC66-Z terminal block AIN1] 1: Analog input (2) [Optional terminal block AIN2] 2: Digital communication option 3: Built-in PLC function output	1	—
i-09	Analog input torque command gain	50.0 to 200.0	150.0	%

・Set i-08 to "1".
・Set G-03 (described in section 5.1) to "0". Only the 0 to ±10V voltage input characteristic can be used.

The torque command value is set as the negative value of the analog input torque gain (i-09) when the input is +10V. When the input is -10V, it is set as the positive value of the analog input torque gain (i-09). (Figure 5.5)
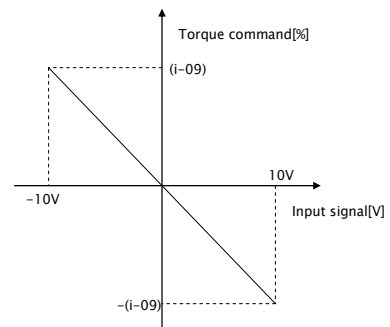
Figure 5.5 Analog input torque command characteristic

５．４ Analog input (3)

The analog signal input(3) to the terminals on IO66-Z can be used as the input value to the rotation speed command value (or frequency command value), torque command value, and built–in PLC function by analog input (3) function.

For usage of analog input(3) function correctly, the correct VF66B inverter parameter setting as mentioned below is required. Please see the instruction manual of the inverter together. Furthermore, for the built-in PLC function, please see VF66 PC Tool manual.

Before usage of analog input(3), Please conduct the adjustment of gain as mentioned below.

Analog input (3) characteristic selection (when IO66-Z option or digital communication option is used)

Display	Item	Set-up range (Item selection)	Default Data	Unit
G-06	Analog input(3) characteristics selection	0: 0 to ±10V 1: 0 to 10V 2: not use 3: Pulse train input (0 to 150kHz)	1	—

* The signal of duty 1:1 with the amplitude of 15V which frequency can change from 0 to 150kHz is inputted into Pulse train input.

The analog signal input into analog input (3) should be connected between the [AIN3] and [G2] terminals of the IO66-Z terminal block TB1, as shown in the following figures. The input analog signal characteristics can be chosen as either "voltage input 0 to ±10V", "voltage input 0 to 10V" or "Pulse train input (0 to 150kHz)", as shown in the above table. Choose an appropriate setting that matches the characteristics of the input signal. Also set the SW3 switch as shown in the following figures.
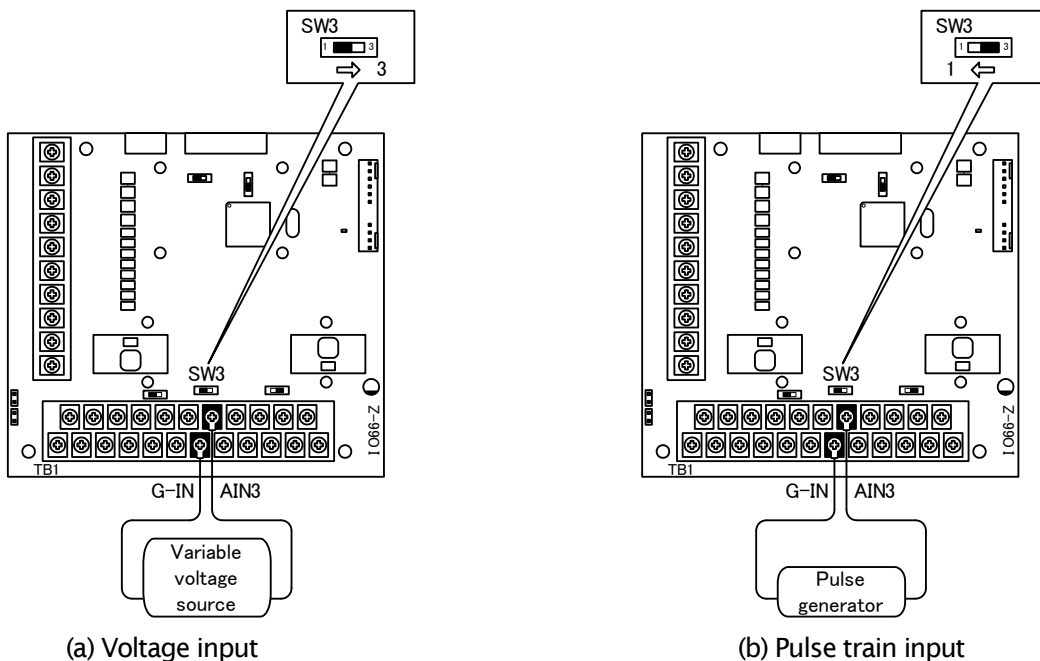

(a) Voltage input   (b) Pulse train input

Figure 5.6   Connection of analog input (3)

5．5 Analog input (3) input gain and offset adjustment

Before usage of analog input (3), gain and offset adjustment are required. Adjustment is conducted under the temperature about 25℃.

Inverter setting parameter related to analog input(3) gain・offset adjustment.

Display	Items	Set-up range (Item selection)	Default Data	Unit
L-07	Analog input(3) gain	50.00 to 150.00	100.00	%
L-08	Analog input(3) offset	-50.00 to 50.00	0.00	%
S-10	Analog input(3)	1. Analog input(3) offset adjustment Input the analog(3) voltage x 1000 Analog input(3) gain adjustment	-	-

（1）Input characteristics "0 to ±10V" or "0 to 10V"

Press [MONI/FNC]key to turn on FNC (function selection) mode (LED-FNC will be lit).

Use [↑][↓]keys to select 「G-06」. Press [SET] key to confirm it.

Use [JOG/→]key to shift the digit to right、and [↑][↓]keys to input "0" and press [SET]keys to confirm it.
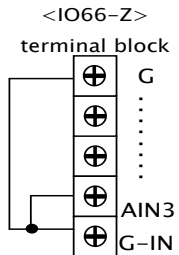
Turn off the inverter power supply, open the front cover, short circuit between [AIN3] [G] [G-IN] terminal on terminal block <TB1> of the <IO66-Z>.

<IO66-Z> terminal block

| G |
| AIN3 |
| G-IN |

⚠ **CAUTION** [Short-Circuit of terminals]
● Before short circuiting terminals, please be sure to turn OFF the inverter. There is a risk of electrical shock.

After power is ON, press [MONI/FNC]key to turn on FNC (function selection) mode (LED-FNC will be lit). Use[JOG/→] [↑][↓]keys to select 「S-10」,and press [SET] key to confirm it.

Use [JOG/→] [↑][↓]key to input 「1040」 and press[SET]key to confirm it.

「S-10」will appear again, press[SET]key to confirm.

Use [JOG/→] [↑][↓]keys to select "1" and press[SET]key to confirm it.
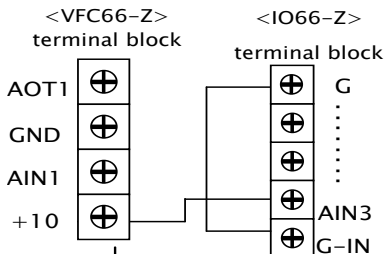
Turn OFF the inverter, open the front cover, and short circuit between [AIN3] on the terminal block <TB1> of the <IO66-Z> and [+10] on the terminal block <TB1>of the control board <VFC66-Z>. Remain short circuited terminals [G] and [G-IN] on the terminal block <TB1> of the <IO66-Z>.

<VFC66-Z> terminal block

| AOT1 |
| GND |
| AIN1 |
| +10 |

<IO66-Z> terminal block

| G |
| AIN3 |
| G-IN |

⚠ **CAUTION**[Short-Circuit of terminals]
● Before short circuiting of terminals, please be sure to turn OFF the inverter. There is a risk of electrical shock.

・After Power is ON, Press[MONI/FNC]key to turn on FNC（function selection）mode.（LED-FNC will be lit）then, use [JOG/→] [↑][↓]keys to select 「S-10」and press [SET]key to confirm.
・Use [JOG/→] [↑][↓]keys to change numbers, input 「1040」 and press [SET]key to confirm.
・「S-10」will appear again、press [SET]key to confirm.
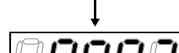
Measure the voltage between the <IO66-Z> terminals [AIN3] and [GND] with a tester and enter the 1000times of the measured value. If measurement is not available, the value"9930" can be used. However accuracy is inferior.

⚠ **CAUTION**[Voltage measurement]
When the voltage between the terminals is measured, please be sure not to touch wirings or terminals. There is a risk of electrical shock.

If 「S-10」appears again, analog input（3）gain(L-07)and analog input（3）offset(L-08) will be changed automatically. Press [MONI/FNC] Key to indicate monitor items.

When adjustment is done, turn OFF the inverter, open the front cover and remove the short circuit wirings installed between terminals, [AIN3]and [+10] of the control board <VFC66-Z>, as well as [G] and [G-IN] on the <IO66-Z>.

５．６ Analog input (3) usage instructions

Before using the analog input (3) function, perform gain and offset adjustment as described in the preceding section.

Through the analog input (3), the input analog signal can be set to be the rotation speed command value (or frequency command value), or built-in PLC input value. Analog input (3) cannot be directly used as torque instructions. (Through the analog input (3), the input analog signal can be set to be the built-in PLC value, and the input value can be used as torque instructions.) The following explanation is for when it is set as the rotation speed command value or the torque command value. For instructions when using it as the input value to the built-in PLC, please refer to the VF66 PCTool manual.

（1）When using the input as a rotation speed command value

When using the analog input as a rotation speed command value, the inverter configuration parameters shown in the following table must be set.

Analog input rotation speed command settings

Display	Items	Set-up Range (Item Selection)	Default Data	Unit
b-10	Rotation speed commanding input place selection	0: Coupled with b-09 1: Analog input (1) [VFC66-Z terminal block AIN1] 2: Console [SET66-Z] 3: Digital communication option 4: Analog input (2) [Optional terminal block AIN2] 5: <BCD66-Z> 6: Analog input (3) [Optional terminal block AIN3] 7: Built-in PLC function output	0	—
G-07	Analog input (3) rotation speed upper limit	[Absolute value Analog Input (3) rotation speed lower limit (G-08)] to [100.0][*]	100.0	%[*]
G-08	Analog input (3) rotation speed lower limit	-[Analog input (3) rotation speed upper limit (G-07)] to [Analog input (3) rotation speed upper limit (G-07)][*]	0.0	%[*]

(*) This is set as a percentage with respect to the maximum rotation speed (configuration parameter A-00). For information about configuration parameter A-00, please refer to the instruction manual of the inverter.

- Set b-10 to "6".
- Set G-06 (described in section 5.1) to a set value that matches the input signal characteristics.

・In the case of voltage input of 0 to ±10V

The rotational direction can be reversed by setting the command input voltage to a negative value. The rotation speed command value is set as the analog input (3) rotation speed upper limit (G-07) when the input is +10V. When the input is -10V, it is set as the negative value of the analog input (3) rotation speed upper limit (G-07). However, it is possible to set a lower limit by setting the analog Input (3) rotation speed lower limit (G-08). (Figure 5.7, left) If the minimum rotation speed (A-01) is other than "0", the rotation speed command absolute value is controlled to prevent falling below the minimum speed. In this case, when the command input voltage is around the 0V range, its behavior shows hysteresis characteristics (It will run forward if started in the forward direction and will run in the minimum reverse speed if started in the reverse direction) as shown in the right side of Figure 5.7.
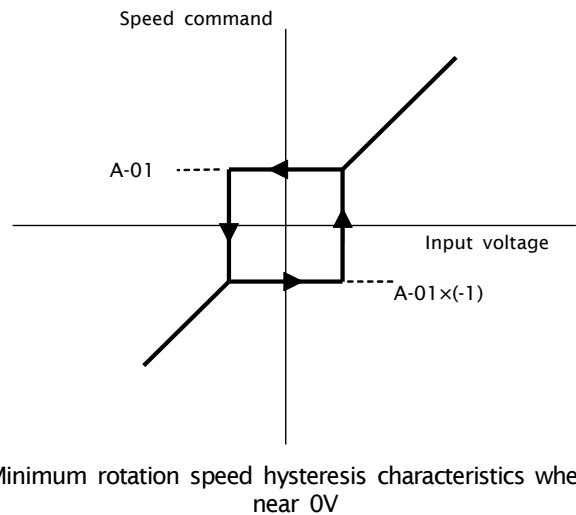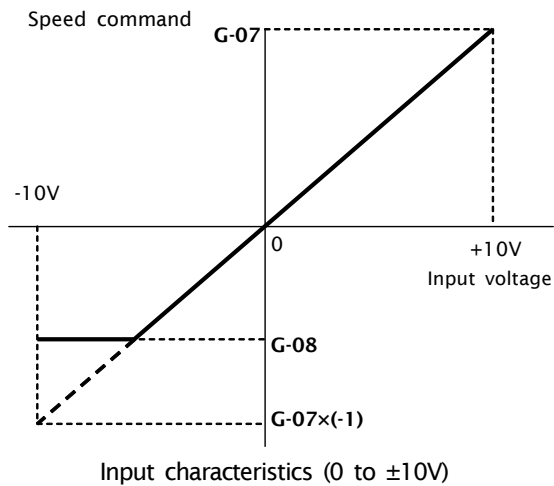
Input characteristics (0 to ±10V)

Minimum rotation speed hysteresis characteristics when near 0V

Figure 5.7 Speed command characteristics with voltage input of 0 to ±10V

・In the case of voltage input of 0 to 10V

The rotation speed command value is set as the analog input (3) rotation speed lower limit (G-08) when the input is 0V. When the input is 10V, it is set as the analog input (3) rotation speed upper limit (G-07). However, this will be set to "0" if the analog input (3) rotation speed lower limit (G-08) has a negative value. (Figure 5.8) If the minimum rotation speed (A-01) is other than "0", the rotation speed command absolute value is controlled to prevent falling below the minimum speed. As a speed command, this only allows forward operation. For reverse operation, a reverse operation command should be used.

Input characteristics when the analog input (3) rotation speed lower limit (G-08) is positive (0 to 10V)

Input characteristics when the analog input (3) rotation speed lower limit (G-08) is negative (0 to 10V)
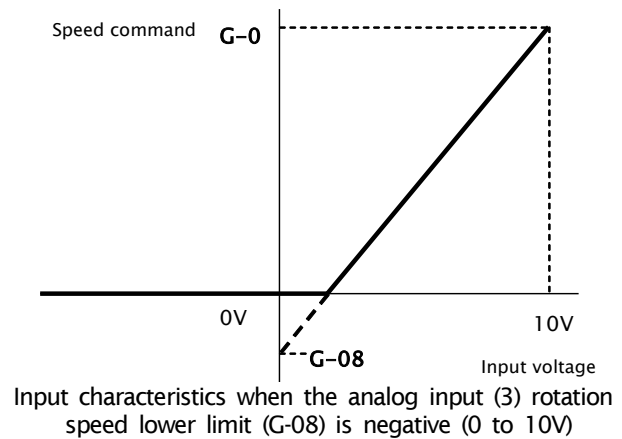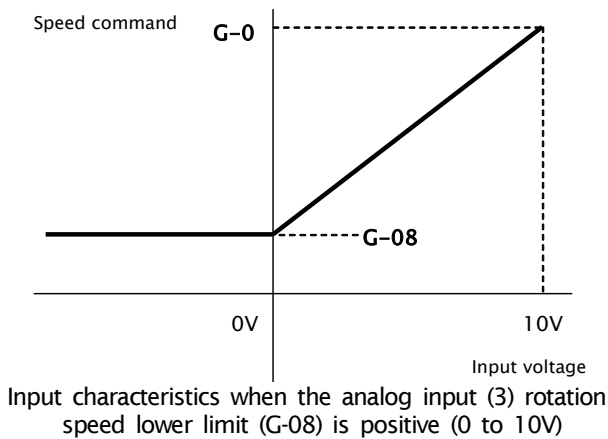
Figure 5.8 Speed command characteristics with voltage input of 0 to 10V

・In the case of pulse train input of 0 to 150kHz

The characteristic of pulse train input is the same as that of voltage input of 0 to 10V. The input of 0 to 10V of "in the case of voltage input of 0 to 10V (Figure 5.8)" of the above figure is used replacing it with 0 to 150kHz.

５．７ Analog output (2)

By analog output (2) function, output voltage of inverter, rotation speed and internal variable of output of built-in PLC function are output as analog signal.

Analog output characteristic output by analog output (2) is "voltage output 0-±10V". Please set the characteristic by setting parameter G-09.

Please refer to the instruction manual of the inverter with this manual.

For built-in PLC function, please refer to the operation manual about "VF66 PC Tool".

Please adjust analog gain and offset before using analog output (2) function.

Analog output setting

Display	Items	Set-up range（Selection items）	Default Data	Unit
G-09	Analog output(2) characteristic selection	0:Output voltage 1:Output current 2:Torque output（V/f mode） 　Torque command（vector mode） 3:Output frequency（V/f mode） 　Motor rotation speed（vector mode） 4:Output frequency command（V/f mode） 　Motor rotation speed command（vector mode） 5:Built-in PLC output 6:Calibration 7:Internal monitor	1	－

Analog output selected by G-09

G-09	Selection items	Output voltage
0	Output voltage	7.5V／200V（200V class） 7.5V／400V（400V class）
1	Output current	5V／inverter rated current
2	Torque output（V/f mode） Torque command（vector mode）	5V／100%
3	Output frequency（V/f mode） Motor rotation speed（vector mode）	10V／maximum frequency（A-00） 10V／maximum rotation speed （A-00）
4	Frequency command（V/f mode）[*1] Motor rotation speed（vector mode）[*1]	10V／maximum frequency（A-00） 10V／maximum rotation speed （A-00）
5	Built-in PLC output [*2]	5V／20000 （100%）[*2]
6	Calibration	5V
7	Internal monitor	－

（＊１） **It is value after acceleration/deceleration control. For more detail, please refer to the instruction manual of the**

inverter.

（＊２） **When built-in PLC output is selected, the value of output resistor "o00009"is output at the rate of 5V/20000.**

For more detail, please refer to the operation manual about "VF66 PC Tool".

Analog output (2) is output between "AOT2" and "G-OT" on the terminal block TB1 of IO66-Z substrate.
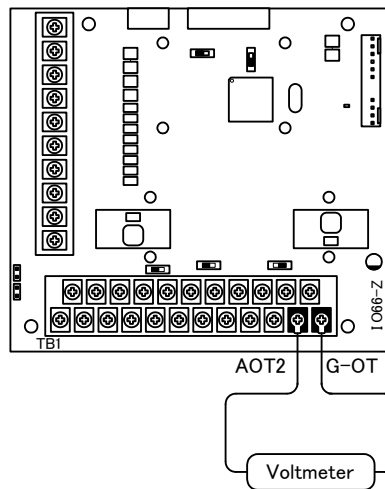

Figure 5.9   Connection of analog output (2)

5．8 Analog output (2) gain offset adjustment

Before usage of analog output(2), please adjust gain offset under the condition of 25℃.

Analog output (2) gain offset adjustment is conducted after the VF66B inverter analog input(1) gain offset adjustment. As to adjustment of analog input (1) gain offset, please see the instruction manual of the inverter.

Analog input(1) gain offset is adjusted when the inverter is shipped from our works, therefore analog input(1) gain offset is not necessary to adjust.

Inverter setting parameter related to analog output gain offset adjustment

Display	Items	Set-up range (Item selection)	Default Data	Unit
L-09	Analog output(2) gain	50.0 to 150.0	100.0	%
L-10	Analog output(2) offset	-50.0 to 50.0	0.0	%
S-09	Analog output (2) adjust	1: Analog output (2) offset adjustment 2: Analog output (2) gain adjustment	-	-

(1) Adjustment of offset and gain of analog output (2)

<VFC66-Z>
terminal block

<IO66-Z>
terminal block

AOT1

GND

AIN1

+10

G

AOT2

G-OT
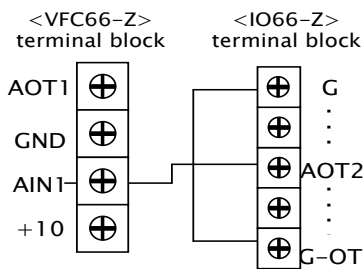
Turn OFF the inverter, open the front cover, and short circuit between terminals [AOT2] on the terminal block <TB1> of the <IO66-Z> and [AIN1] on the terminal block <TB1> of the control board <VFC66-Z> and so as [G] and [G-OT] on terminal block <TB1> of the <IO66-Z>.

⚠ **CAUTION** [Short circuiting of terminals]

● Before short circuiting terminals, please be sure to turn OFF the inverter. There is a risk of electrical shock.

After power is ON, press [MONI/FNC] key to turn on FNC (function selection) mode. (LED-FNC will be lit).

· After power is ON, press [MONI/FNC] key to turn on FNC (function selection) mode. (LED-FNC will be lit). Use [JOG/→] [↑][↓] keys to select "b-17" then press [SET] to confirm it.

· Use [JOG/→] [↑][↓]keys to input "0" and press[SET]key to confirm it.
· 「b-17」 appears again.

· Use [JOG/→] [↑][↓]keys to select 「G-09」 and press [SET]key to confirm it.
· Use [JOG/→] [↑][↓]keys to input "0" and press [SET]key to confirm it.
· 「G-09」 will appear again.

· Use[JOG/→] [↑][↓]keys to select 「S-09」 and press [SET]key to confirm it.
· Use[JOG/→] [↑][↓]keys to input 「1040」 and press [SET]key to confirm it.
· 「S-09」 will appear again, press [SET]key to confirm it.
· Use [JOG/→] [↑][↓]keys to input "1" and press [SET]key to confirm it.
· 「S-09」 will appear again.

· Use [JOG/→] [↑][↓]keys to select 「G-09」 and press [SET]key to confirm it.
· Use [JOG/→] [↑][↓]keys to input "6" and press[SET]key to confirm it.
· 「G-09」 will appear again.

· Use [JOG/→] [↑][↓]keys to select 「S-09」 and press[SET]key to confirm it.
· Use [JOG/→] [↑][↓]keys to input 「1040」 and press [SET]key to confirm it
· 「S-09」 will appear again and press [SET]key to confirm it.
· Use [JOG/→] [↑][↓]keys to input "2" and press [SET]key to confirm it.
· If "S-09" appears again, analog output (2) gain (L-09) and analog output (2) offset (L-10) will be changed automatically.
· Press [MONI/FNC] to indicate monitor items.
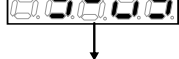
When adjustment is done, turn OFF the inverter, open the front cover, and remove the short circuit wirings installed between terminals [AOT2] on the <IO66-Z> and [AIN1] on the control board <VFC66-Z>, as well as [G] and [G-OT] on the <IO66-Z>. Reset the setting of [G-09] and [b-17].

5．9 **Analog output (3)**

By analog output (3) function, output voltage of inverter, rotation speed and internal variable of output of built-in PLC function are output as analog signal.

Analog output characteristic output by analog output (3) is "voltage output 0 to ±10V". Please set the characteristic by setting parameter G-10.

Please refer to the instruction manual of the inverter with this manual.

For built-in PLC function, please refer to the operation manual about "VF66 PC Tool".

Please adjust analog gain and offset before using analog output (3) function.

Analog output (3) characteristic selection

Display	Items	Set-up range (Item selection)	Default Data	Unit

G-10	Analog output(3) characteristics selection	0: Output voltage
		1: Output current
		2: Torque output (V/f mode)
		    Torque command (Vector mode)
		3: Output frequency (V/f mode)
		    Motor speed (Vector mode)
		4: Output frequency command (V/f mode)
		    Motor speed command (Vector mode)
		5: Built-in PLC output
		6: Calibration
		7: Internal monitor
		8: Output voltage (4 to 20mA)
		9: Output current (4 to 20mA)
		10: Torque output (V/f mode) (4 to 20mA)
		    Torque command (Vector mode) (4 to 20mA）
		11: Output frequency (V/f mode) (4 to 20mA)
		    Motor speed (Vector mode)(4 to 20mA）
		12: Output frequency command (V/f mode) (4 to 20mA)
		    Motor speed command (Vector mode) (4 to 20mA)
		13: Built-in PLC output (4 to 20mA）
		14: Calibration (12mA output)
			1	―

Analog output set at G-10 (Selection items 0 to 14)

G-10	Selection items	Output voltage or output current
0	Output voltage	7.5V/200V (200V class) 7.5V/400V (400V class)
1	Output current	5V/inverter rated current
2	Torque output (V/f mode) Torque command (Vector mode)	5V/100%
3	Output frequency (V/f mode) Motor speed (Vector mode)	10V/maximum frequency (A-00) 10V/maximum speed (A-00)
4	Frequency command (V/f mode)[1] Motor speed command (Vector mode)[1]	10V/maximum frequency (A-00) 10V/maximum speed (A-00)
5	Built-in PLC output[2]	5V/ 20000(100%)[2]
6	Calibration	Outputs 5V
7	Internal monitor	—
8	Output voltage	16mA/200V (200V class) 16mA/400V (400V class)
9	Output current	12mA/ inverter rated current
10	Torque output (V/f mode) Torque command (Vector mode)	12mA/100%
11	Output frequency (V/f mode) Motor speed (Vector mode)	20mA/maximum frequency (A-00) 20mA/maximum speed (A-00)
12	Frequency command (V/f mode)[1] Motor speed command (Vector mode)[1]	20mA/maximum frequency (A-00) 20mA/maximum speed (A-00)
13	Built-in PLC output[3]	12mA/ 20000(100%)[3]
14	Calibration	Outputs 12mA

（＊1） It is value after acceleration/deceleration control. For more detail, please refer to the instruction manual of the

    inverter.

（＊2） When built-in PLC output is selected, the value of output resistor "o0000A"is output at the rate of 5V/20000. For more detail, please refer to the operation manual about "VF66 PC Tool".

（＊3） When built-in PLC output is selected, the value of output resistor "o0000A"is output at the rate of 20mA/20000. For more detail, please refer to the operation manual about "VF66 PC Tool".

Analog output (3) is output between "AOT3"and "G-OT" on the terminal block of IO66-Z substrate. Please set switch "SW5" according to the characteristic of analog signal as following.

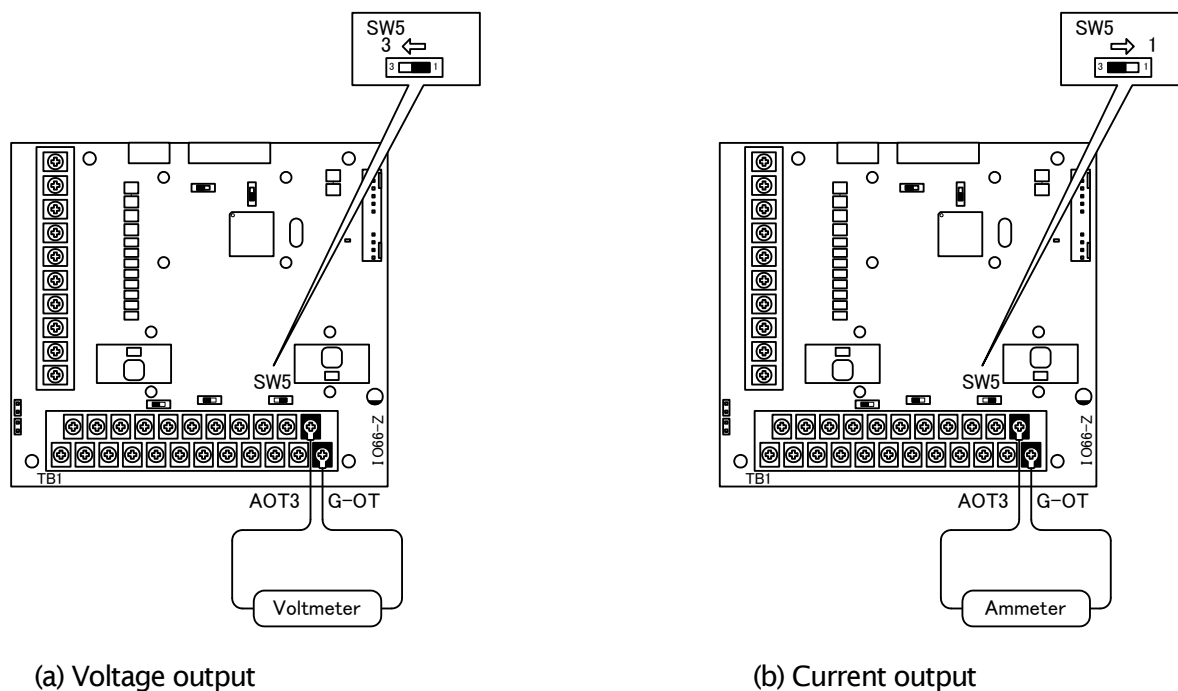(a) Voltage output   (b) Current output

Figure 5.10   Connection of analog output (3)

５．１０ Analog output (3) gain offset adjustment

Before usage of analog output(3), please adjust gain offset under the condition of 25℃.

Analog output (3) gain offset adjustment is conducted after the VF66B inverter analog input(1) gain offset adjustment. As to adjustment of analog input (1) gain offset, please see the instruction manual of the inverter.

Analog input (1) gain offset is adjusted when the inverter is shipped from our works, therefore analog input (1) gain offset is not necessary to adjust.

Inverter setting parameter related to analog output gain offset adjustment

Display	Items	Set-up range (Item selection)	Default Data	Unit
L-11	Analog output(3) gain	50.0 to 150.0	100.0	%
L-12	Analog output(3) offset	-50.0 to 50.0	0.0	%
S-11	Analog output (3) adjust	1: Analog output (3) offset adjustment 2: Analog output (3) gain adjustment	-	-

（1）Output characteristics "0 to ±10V"

<VFC66-Z>
terminal block

<IO66-Z>
terminal block

AOT1 ⊕
GND ⊕
AIN1 ⊕
+10 ⊕

⊕ G
⊕
⊕ AOT3
⊕
⊕ G-OT
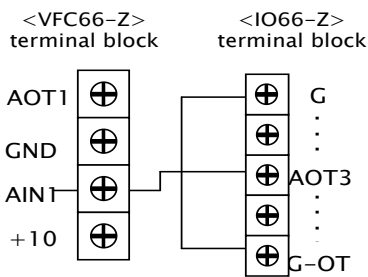
Turn OFF the inverter, open the front cover, and short circuit between terminals [AOT3] on the terminal block <TB1> of the <IO66-Z> and [AIN1] on the <IO66-Z> and so as [G] and [G-OT] on terminal block <TB1> of the <IO66-Z>.

> ⚠ **CAUTION** [Short circuiting of terminals]
> ● Before short circuiting terminals, please be sure to turn OFF the inverter. There is a risk of electrical shock.

After power is ON, press [MONI/FNC] key to turn on FNC (function selection) mode. (LED-FNC will be lit).

・After power is ON, press [MONI/FNC] key to turn on FNC (function selection) mode.
 (LED-FNC will be lit). Use [JOG/→] [↑][↓] keys to select "b-17" then press [SET] to confirm it.

・Use [JOG/→] [↑][↓]keys to Input "0" and press [SET] key to confirm it.
・「b-17」appears again.

・Use [JOG/→] [↑][↓]keys to select 「G-10」and press [SET]key to confirm it.
・Use [JOG/→] [↑][↓]keys to input "0" and press [SET]key to confirm it.
・「G-10」will appear again.

・Use[JOG/→] [↑][↓]keys to select 「S-11」and press [SET]key to confirm it.
・Use[JOG/→] [↑][↓]keys to input 「1040」and Press [SET]key to confirm it.
・「S-11」will appear again, press [SET]key to confirm it.
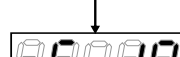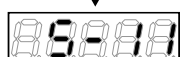・Use [JOG/→] [↑][↓]keys to input "1" and press [SET]key to confirm it.
・「S-11」will appear again.

・Use [JOG/→] [↑][↓]keys to select 「G-10」and press [SET]key to confirm it.
・Use [JOG/→] [↑][↓]keys to input "6" and press[SET]key to confirm it.
・「G-10」will appear again.

・Use [JOG/→] [↑][↓]keys to select 「S-11」and press[SET]key to confirm it.
・Use [JOG/→] [↑][↓]keys to input 「1040」and press [SET]key to confirm it.
・「S-11」will appear again and press [SET]key to confirm it.
・Use [JOG/→] [↑][↓]keys to input "2" and press [SET]key to confirm it.
・If "S-11" appears again, analog output (3) gain (L-11) and analog output (3) offset (L-12) will be changed automatically.
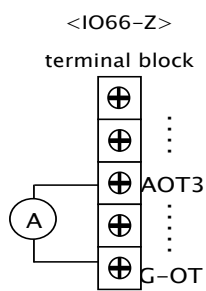・Press [MONI/FNC] to indicate monitor items.

When adjustment is done, turn OFF the inverter, open the front cover, and remove the short circuit wirings installed between terminals [AOT3] on the <IO66-Z> and [AIN1] on the control board <VFC66-Z>, as well as [G] and [G-OT] on the <IO66-Z>. Reset the setting of [G-10] and [b-17].

（2）Output characteristics "4 to 20mA"

<IO66-Z>

terminal block

Turn OFF the inverter, open the front cover, and connect ammeter between terminals [AOT3] and [G-0T] on the terminal block <TB1> of the <IO66-Z>. Stay inverter off, and turn side 1 on SW5.
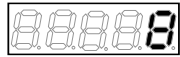
⚠ **CAUTION**[Connecting Ammeter]

● Before connecting ammeter, please be sure to turn OFF the inverter.
  There is a risk of electrical shock.
● Before sifting the switch, please be sure to turn OFF the inverter.
  There is a risk of electrical shock.

`09-AF`

After power is ON, press [MONI/FNC] key to turn on FNC (function selection) mode. (LED-FNC will be lit)

`G-10`
`8`
`G-10`

・Use [JOG/→] [↑][↓]keys to select 「G-10」 and Press [SET]to confirm it.
・Use [JOG/→] [↑][↓]keys to input "8" and press[SET]key to confirm it.
・ 「G-10」 will appear again.

`L-12`
`0`

・Use[JOG/→] [↑][↓]keys and select 「L-12」 .
・Adjust analog output(3) offset 「L-12」 so that the display of ammeter is 4mA.

`G-10`
`14`
`G-10`

・Use[JOG/→] [↑][↓]key to select 「G-10」 and [SET]key to confirm it.
・Use [JOG/→] [↑][↓]key to input "14" and press [SET]key to confirm it.
・ 「G-10」 will appear again.

`L-11`
`0`

・Use [JOG/→] [↑][↓]keys to select 「L-11」 .
・Adjust analog output(3) gain(L-11) so that the display of ammeter could be 12mA.
・Press [MONI/FNC]key to display the monitor item.

When adjustment is done, turn OFF the inverter, open the front cover, and remove the ammeter installed between terminals [AOT3] and [G-OT] on the <IO66-Z>. Reset the setting of [G-10] for adjustment.

Chapter 6　PG input/output function

PG input/output functionality is used when driving a motor from the signal which detected the magnetic pole location and velocity of the rotor by the sensor (PG). PG is a correspondence only a complementary output with 12V power source. The instruction manual of the inverter is referred to for a selection in PG mode, and an inverter mode change.

6．1 PG input signal

In order to use PG input/output functionality, it is necessary to set correctly the inverter setups parameter shown in the following table according to the operation mode of an inverter, and PG specification to be used. Please also refer to the instruction manual of the inverter collectively.

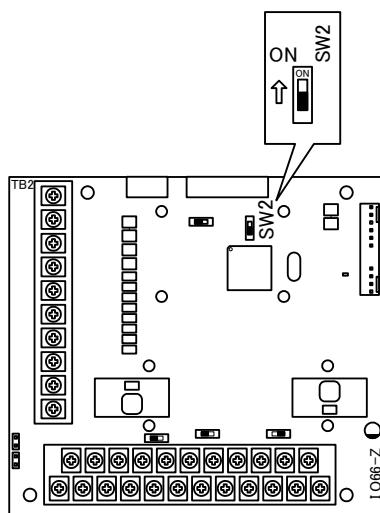※**When switch SW2 on IO66-Z is ON, the input of PG signal is effective.**

Figure 6.1　PG signal input switching

The inverter setups parameter of PG input signal setups

Display	Item	Set-up range (Item selection)	Set-up resolution	Default Data	Unit
A-10	PG Selection	V/f mode	(PG not used)	—	—
		Induction motor vector control mode	0: S-mode　Sensor-less drive 1: V-mode　with PG (AB phase input)	0	—
		ED motor vector control mode	0: S-mode　Sensor-less drive 1: V-mode　with PG (ABZ phase input) [*1] 2: P-mode　with PG (ABUVW phase input) 3: RL-mode with resolver (resolution 10bit) [*2] 4: RH-mode　with resolver (resolution 12bit) [*2]	0	—

（＊1）**For special motors**
（＊2）**An option is required**

（1）In the case of induction motor vector control mode

Please set 1 as the setups parameter A-10 shown in the upper table, and as shown in Fig. 6.2, connect PG wire to terminal block TB2 of IO66-Z. （Since it is not used, please do not connect U/Z, V, and W termination of TB2）

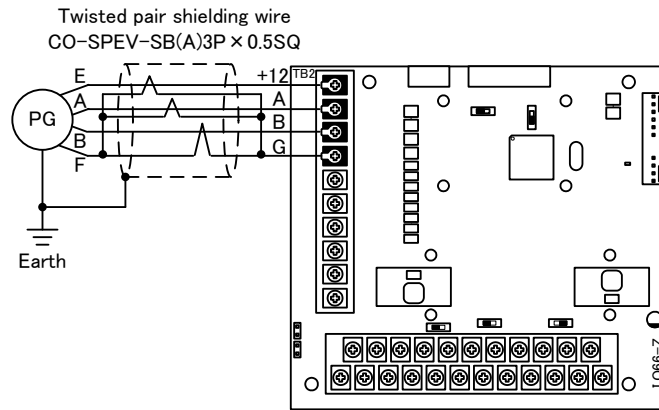The recommendation cable of PG wire is CO-SPEV-SB(A)3Px0.5SQ (made by Hitachi Cable).

Figure 6.2　PG wire interconnection of an induction motor

（2）In the case of induction motor vector control mode

Please set 2 as the setups parameter A-10 shown in the upper table, and as shown in Fig. 6.3, connect PG wire to terminal block TB2 of IO66-Z. (As the setting value of "1" for A-10 is used for a special motor, it should not be selected for normal operation.)

The recommendation cable of PG wire is CO–SPEV–SB(A)3Px0.5SQ (made by Hitachi Cable). For ED motor PG connection, straight plugs (MS3106B–20–29S) and cable clamps (MS3057–12A) (Japan Aviation Electronics Industry, Ltd.) are required.
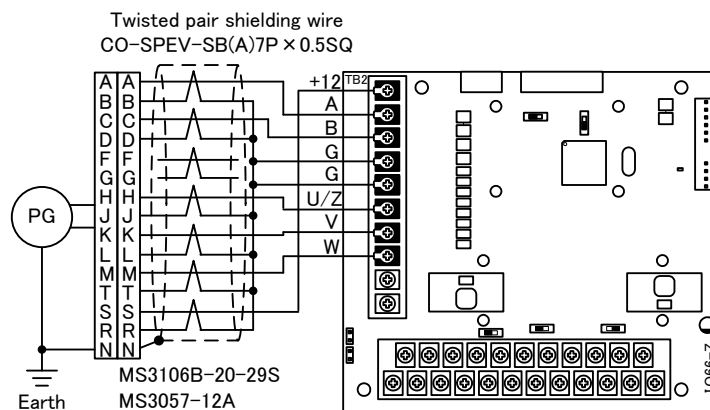

Figure 6.3　PG wire interconnection of an ED motor

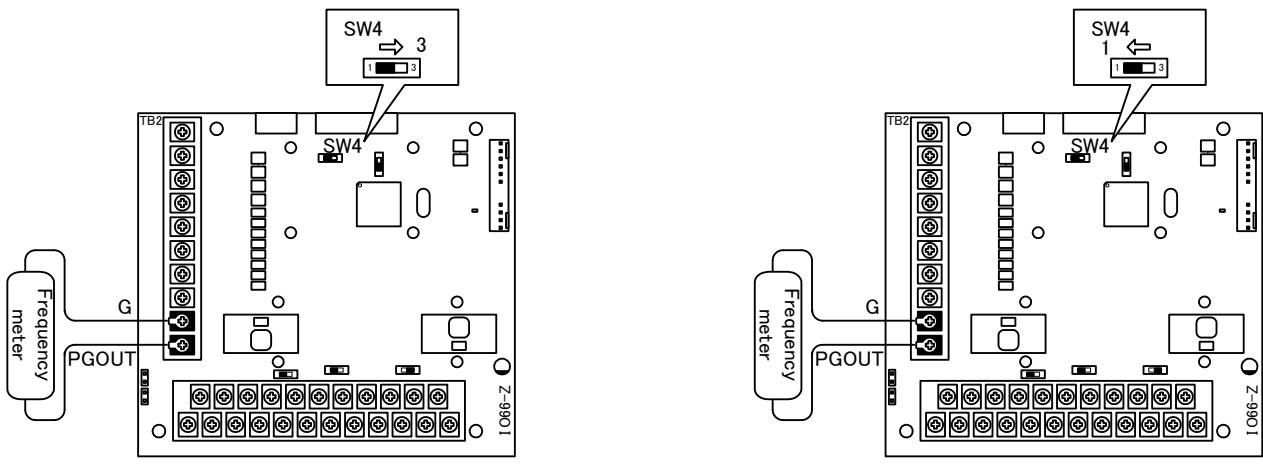| ⚡ **DANGER** [Wiring] |
|---|
| ● When wiring PG, an inverter power source is certainly turned off.
　Failure to do so may cause an electric shock, personal injury, equipment failure or malfunction.
● Never connect the G terminal to earth.
　Doing so may cause equipment failure or damage. |

⚡ **DANGER** [Switch]
●   Change of a switch is performed by certainly turning off an inverter.   Failure to do so may cause an electric shock, personal injury, equipment failure or malfunction.

６．２ **PG output signal**

  PG frequency dividing signal is outputted from A signal of PG input. Peak value is about 10V and duty1:1. If SW4 of IO66-Z is switched to side of 3, 1 / 4PG frequency divided signal is outputted, and if SW4 is switched to side of 3, 1 / 2PG frequency divided signal is outputted. Please switch according to a destination.

(a) 1 / 4PG frequency divided output   (b) 1 / 2PG frequency divided output

Figure 6.4　PG signal output

⚡ **DANGER** [Wiring]

●   Before connecting anything to the terminals, please be sure to turn off the inverter.
      Failure to do so may cause an electric shock, personal injury, equipment failure or malfunction.
 ●   Never connect the G terminal to earth.
      Doing so may cause equipment failure or damage.

In addition, the contents of this the "operating manual" may be changed without a preliminary announcement by specification change of a product etc. Please understand that it may differ from the contents of the "operating manual" enclosed by the model of purchase, and the contents of the "operating manual" posted on our homepage.

Please have a look from our homepage about the newest "operating manual."

Contents of this manual are subject to change without notice.

TIM017[A]_20140624